

# Linearly Converging Error Compensated SGD

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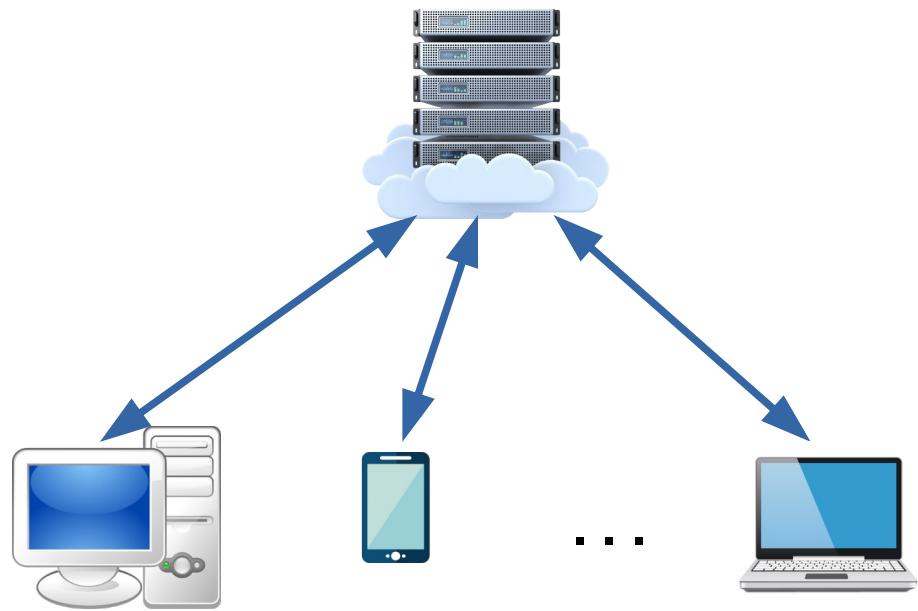


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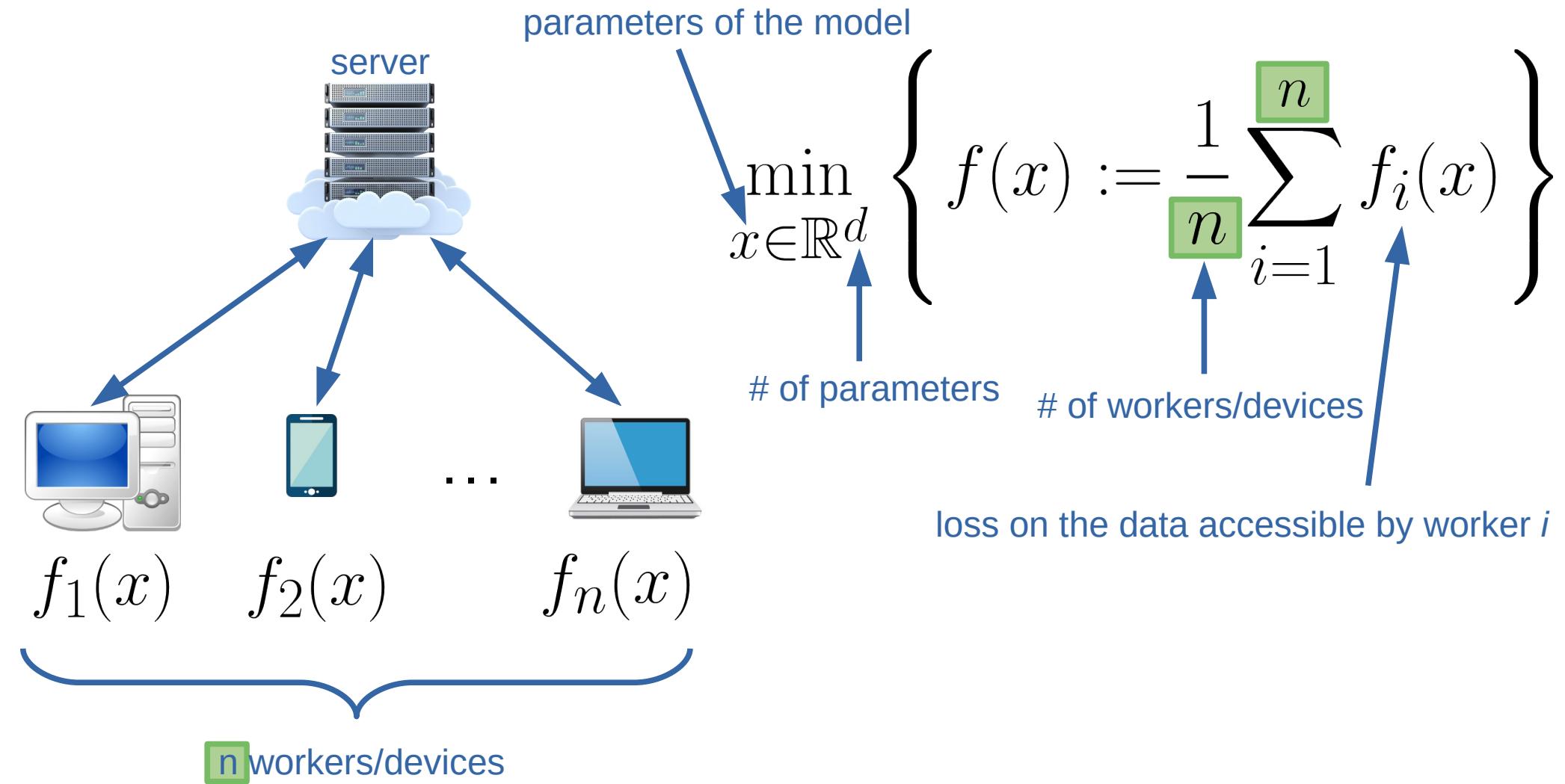


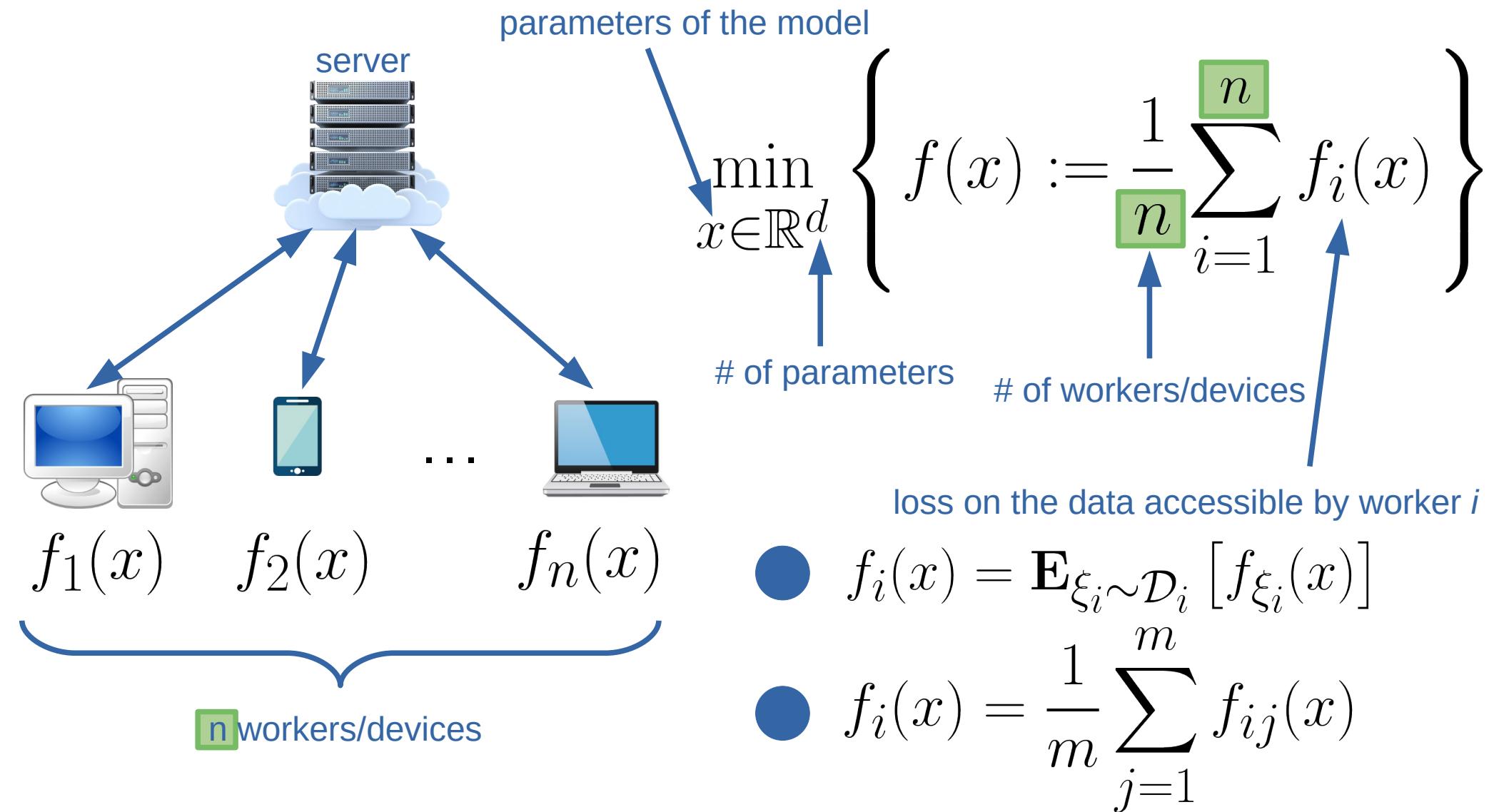
Peter Richtárik  
Professor of Computer Science  
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# 1. The Problem



$$\min_{x \in \mathbb{R}^d} \left\{ f(x) := \frac{1}{n} \sum_{i=1}^n f_i(x) \right\}$$





# Assumptions

$$\|\nabla f_i(x) - \nabla f_i(y)\| \leq L\|x - y\|$$

$$f_i(x) - f_i(y) \geq \langle \nabla f_i(y), x - y \rangle$$

- $f_1, f_2, \dots, f_n$  – L-smooth and convex

# Assumptions

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$$f_i(x) - f_i(y) \geq \langle \nabla f_i(y), x - y \rangle$$

- $f_1, f_2, \dots, f_n$  – L-smooth and convex
- $f$  – strongly quasi-convex

$$f(x^*) \geq f(x) + \langle \nabla f(x), x^* - x \rangle + \frac{\mu}{2} \|x^* - x\|^2$$

the solution of the problem

## 2. Parallel SGD

1

Server broadcasts the parameters



1 Server broadcasts the parameters

2 Devices compute **stochastic gradients** in parallel

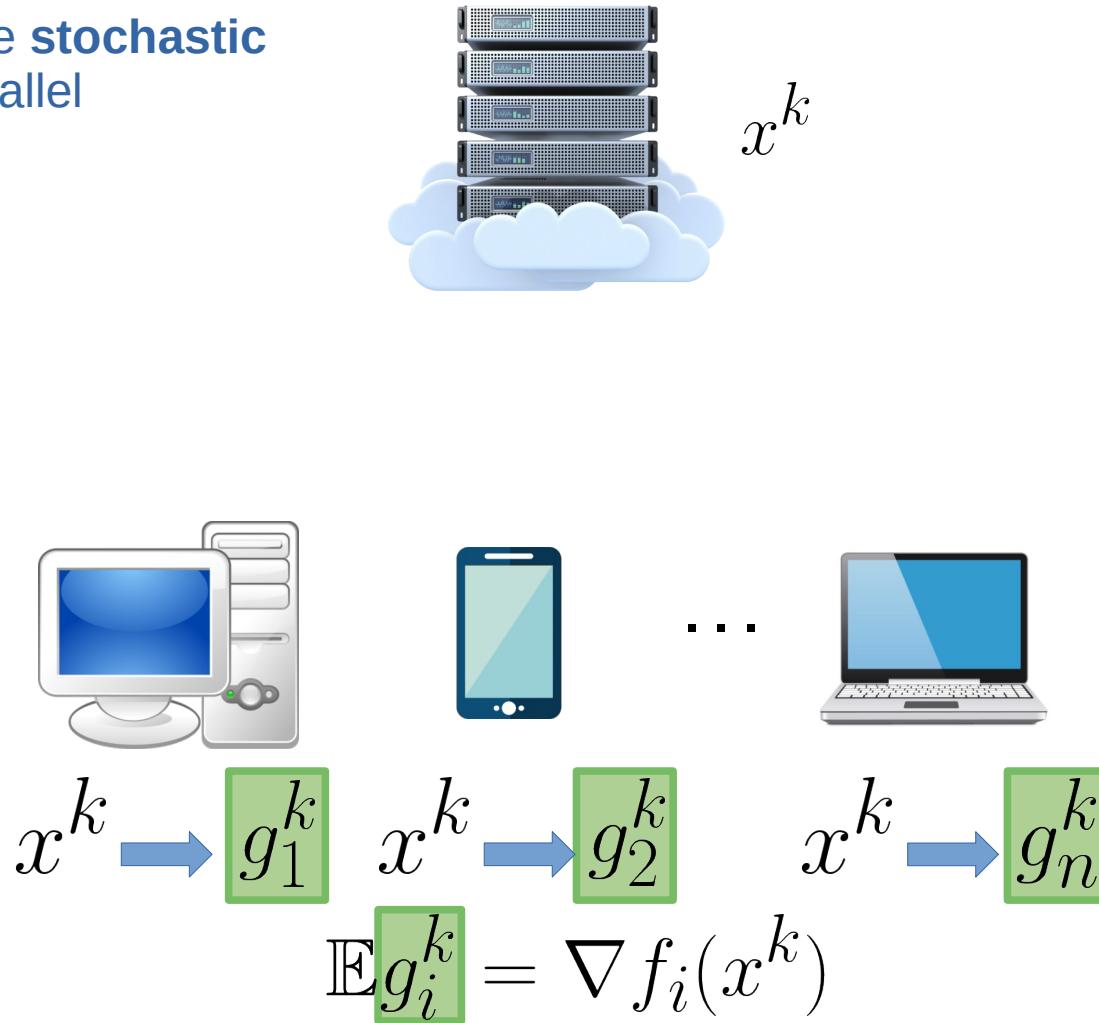
 $x^k$ 

...

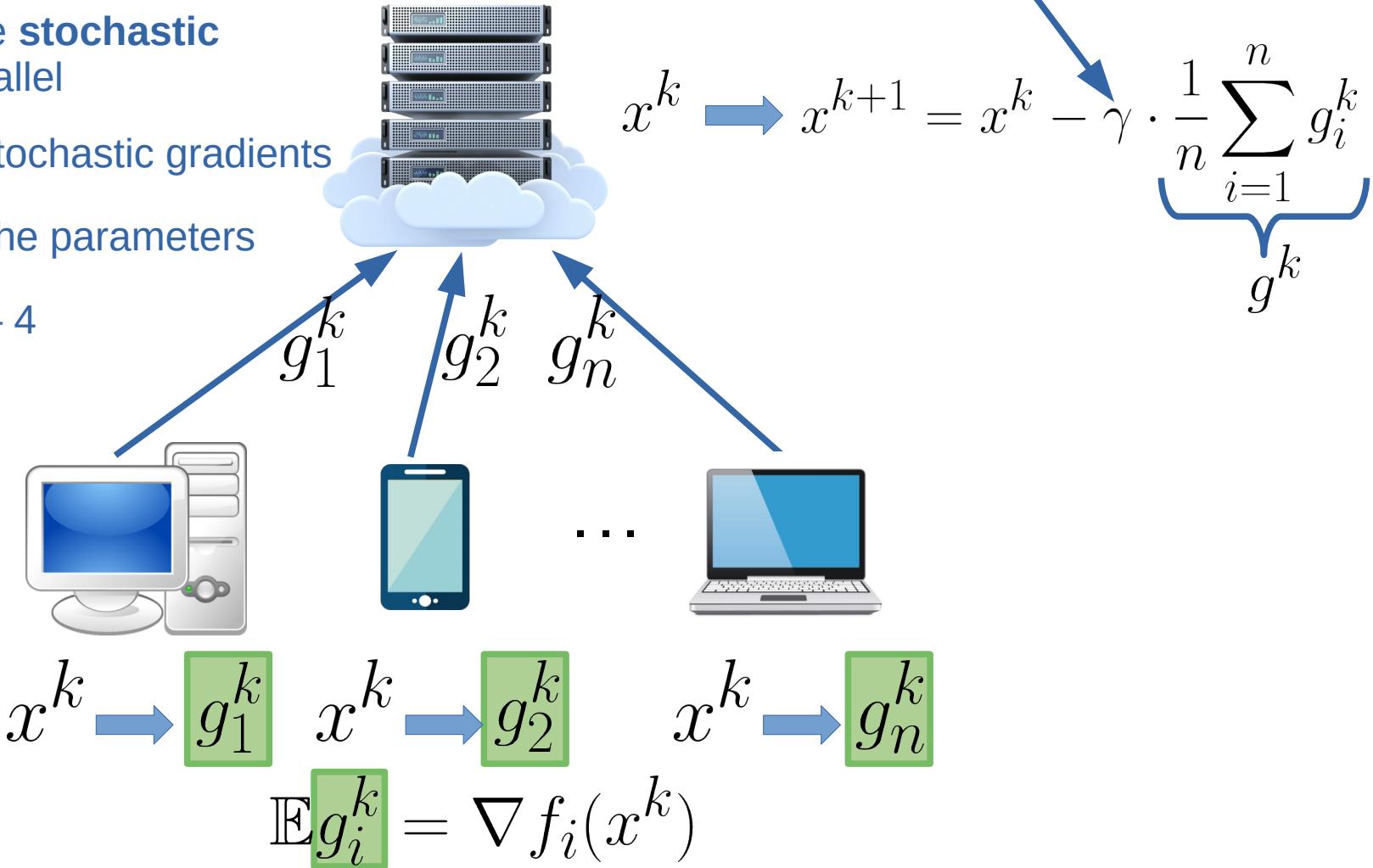
 $x^k \rightarrow g_1^k$  $x^k \rightarrow g_2^k$  $x^k \rightarrow g_n^k$

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- 1 Server broadcasts the parameters
- 2 Devices compute **stochastic gradients** in parallel
- 3 Server gathers stochastic gradients
- 4 Server updates the parameters
- 5 Repeat steps 1 – 4



1 Server broadcasts the parameters

2 Devices compute **stochastic gradients** in parallel

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stepsize

$$x^k \rightarrow x^{k+1} = x^k - \gamma \cdot \frac{1}{n} \sum_{i=1}^n g_i^k$$

$\underbrace{\phantom{\sum_{i=1}^n}}_{g^k}$

communication is a bottleneck

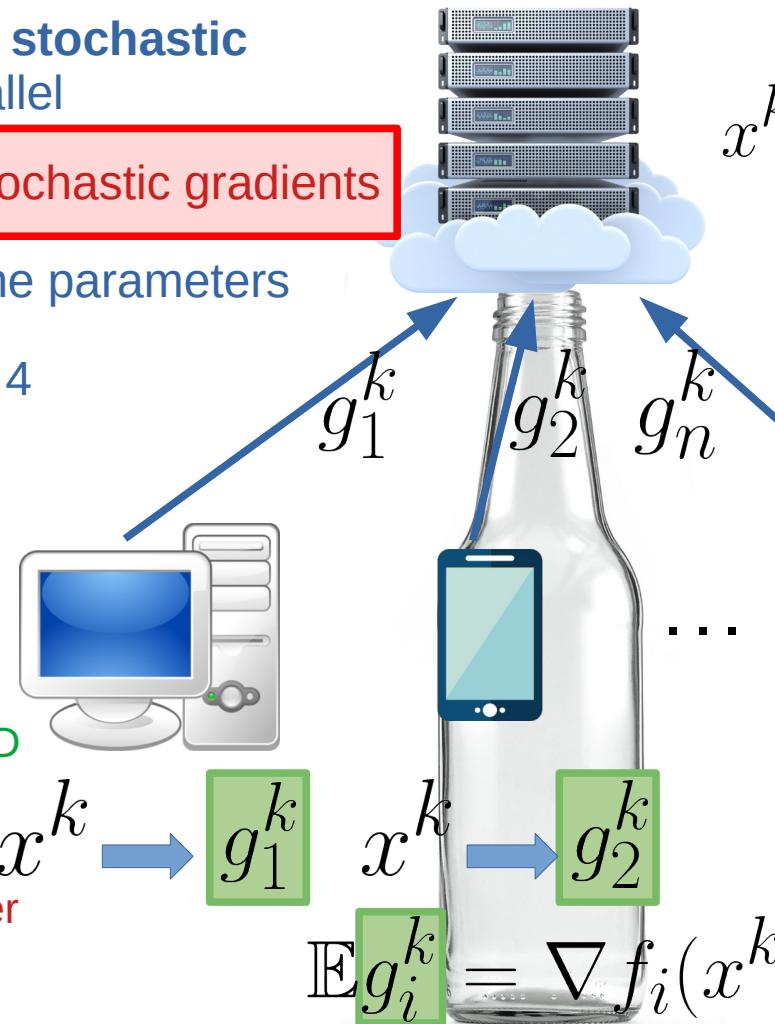
Good news:

✓ Very simple algorithm

✓ Can be much faster than non-parallel SGD

Issues:

✗ Overload of the server



$$\mathbb{E} g_i^k = \nabla f_i(x^k)$$

# 3. Communication Bottleneck

# How to Handle Communication Bottleneck?

- Change the topology of the network → Decentralized optimization
- Do more work on each worker and communicate less → Local-SGD/Federated Averaging

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Example:

$$\text{Send } g_i^k = \begin{pmatrix} 1 \\ -15 \\ 0.2 \\ -7 \\ 10 \end{pmatrix} \rightarrow \text{Send } \mathcal{C}(g_i^k) = \begin{pmatrix} 0 \\ -15 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

# How to Handle Communication Bottleneck?

- Change the topology of the network → Decentralized optimization
  - Do more work on each worker and communicate less → Local-SGD/Federated Averaging
  - Send less information to reduce the communication cost
    - Example: Send  $g_i^k = \begin{pmatrix} 1 \\ -15 \\ 0.2 \\ -7 \\ 10 \end{pmatrix}$
    - Compression operator
    - Send  $\mathcal{C}(g_i^k) = \begin{pmatrix} 0 \\ -15 \\ 0 \\ 0 \\ 0 \end{pmatrix}$
- We focus on this approach

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Example:

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Compression operator

$$\text{Send } C(g_i^k) =$$

$$\begin{pmatrix} 0 \\ -15 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

*What are the options for choosing this?*

# Compression Operators



Unbiased compressors  
(quantizations)

$$x \rightarrow Q(x) \quad \mathbb{E}[Q(x)] = x$$



Biased compressors

$$x \rightarrow C(x)$$

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Biased compressors

$$\mathbb{E}\|Q(x) - x\|^2 \leq \omega \|x\|^2$$

$$x \rightarrow C(x) \quad \mathbb{E}\|C(x) - x\|^2 \leq (1 - \delta)\|x\|^2$$

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$$\mathbb{E}\|C(x) - x\|^2 \leq (1 - \delta)\|x\|^2$$

Example: RandK (for K = 2)

$$\begin{pmatrix} 1 \\ -15 \\ 0.2 \\ -7 \\ 10 \end{pmatrix} \xrightarrow{\text{for unbiasedness}} \overset{5}{\overbrace{2}} \cdot \begin{pmatrix} 1 \\ 0 \\ 0 \\ -7 \\ 0 \end{pmatrix}$$

Example: TopK (for K = 2)

$$\begin{pmatrix} 1 \\ -15 \\ 0.2 \\ -7 \\ 10 \end{pmatrix} \xrightarrow{\text{Pick K = 2 components with largest absolute value}} \begin{pmatrix} 0 \\ -15 \\ 0 \\ 0 \\ 10 \end{pmatrix}$$

Pick K = 2 components uniformly at random

Pick K = 2 components with largest absolute value

# Methods with Unbiased Compressors



## QSGD



Alistarh, Dan, Demjan Grubic, Jerry Li, Ryota Tomioka, and Milan Vojnovic. "**QSGD: Communication-efficient SGD via gradient quantization and encoding.**" In *Advances in Neural Information Processing Systems*, pp. 1709-1720. 2017.



## TernGrad



Wen, Wei, Cong Xu, Feng Yan, Chunpeng Wu, Yandan Wang, Yiran Chen, and Hai Li. "**Terngrad: Ternary gradients to reduce communication in distributed deep learning.**" In *Advances in neural information processing systems*, pp. 1509-1519. 2017.



## DQGD



Khirirat, Sarit, Hamid Reza Feyzmahdavian, and Mikael Johansson. "**Distributed learning with compressed gradients.**" arXiv preprint arXiv:1806.06573 (2018).



## DIANA



Mishchenko, Konstantin, Eduard Gorbunov, Martin Takáč, and Peter Richtárik. "**Distributed learning with compressed gradient differences.**" arXiv preprint arXiv:1901.09269 (2019).



Horváth, Samuel, Dmitry Kovalev, Konstantin Mishchenko, Sebastian Stich, and Peter Richtárik. "**Stochastic distributed learning with gradient quantization and variance reduction.**" arXiv preprint arXiv:1904.05115 (2019).



**Sublinear convergence rates even in the case when workers quantize full gradients**

**Converges linearly when workers quantize full gradients**

# Parallel SGD with Biased Compressor Can Diverge at Exponential Rate



Beznosikov, Aleksandr, Samuel Horváth, Peter Richtárik, and Mher Safaryan. "On Biased Compression for Distributed Learning." arXiv preprint arXiv:2002.12410 (2020).

$$n = d = 3$$

$$f_1(x) = \langle a, x \rangle^2 + \frac{1}{4} \|x\|^2 \quad f_2(x) = \langle b, x \rangle^2 + \frac{1}{4} \|x\|^2 \quad f_3(x) = \langle c, x \rangle^2 + \frac{1}{4} \|x\|^2$$

$$a = (-3, 2, 2)^\top \quad b = (2, -3, 2)^\top \quad c = (2, 2, -3)^\top$$

$$x^0 = (t, t, t)^\top$$

In this case Parallel SGD with Top1 compression operator satisfies

$$x^k = \left(1 + \frac{11\gamma}{6}\right)^k x^0$$

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One can fix this using one special trick called ***error-compensation***

# 4. Error-Compensated SGD

# Papers on EC-SGD



Seide, Frank, Hao Fu, Jasha Droppo, Gang Li, and Dong Yu. "**1-bit stochastic gradient descent and its application to data-parallel distributed training of speech dnns.**" *In Fifteenth Annual Conference of the International Speech Communication Association*. 2014.



Stich, Sebastian U., Jean-Baptiste Cordonnier, and Martin Jaggi. "**Sparsified SGD with memory.**" *In Advances in Neural Information Processing Systems*, pp. 4447-4458. 2018.



Karimireddy, Sai Praneeth, Quentin Rebjock, Sebastian Stich, and Martin Jaggi. "**Error Feedback Fixes SignSGD and other Gradient Compression Schemes.**" *In International Conference on Machine Learning*, pp. 3252-3261. 2019.



Stich, Sebastian U., and Sai Praneeth Karimireddy. "**The error-feedback framework: Better rates for SGD with delayed gradients and compressed communication.**" arXiv preprint arXiv:1909.05350 (2019).

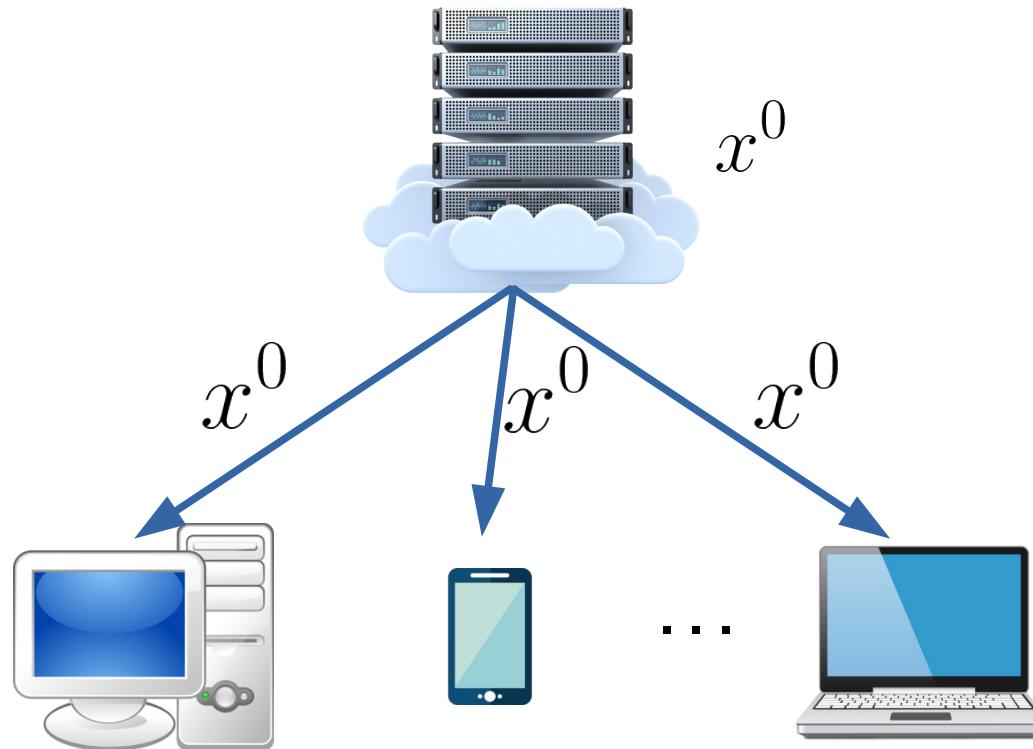


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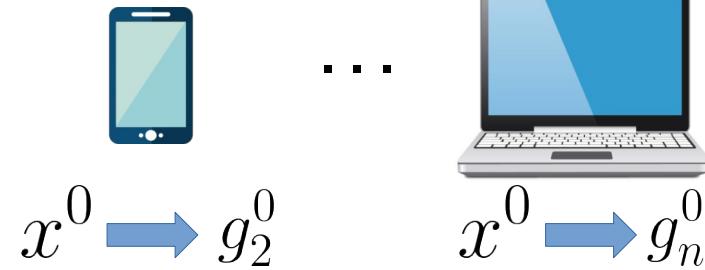
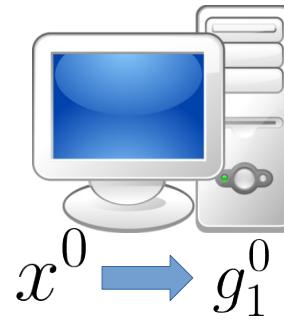
Server broadcasts the parameters

# Step 1



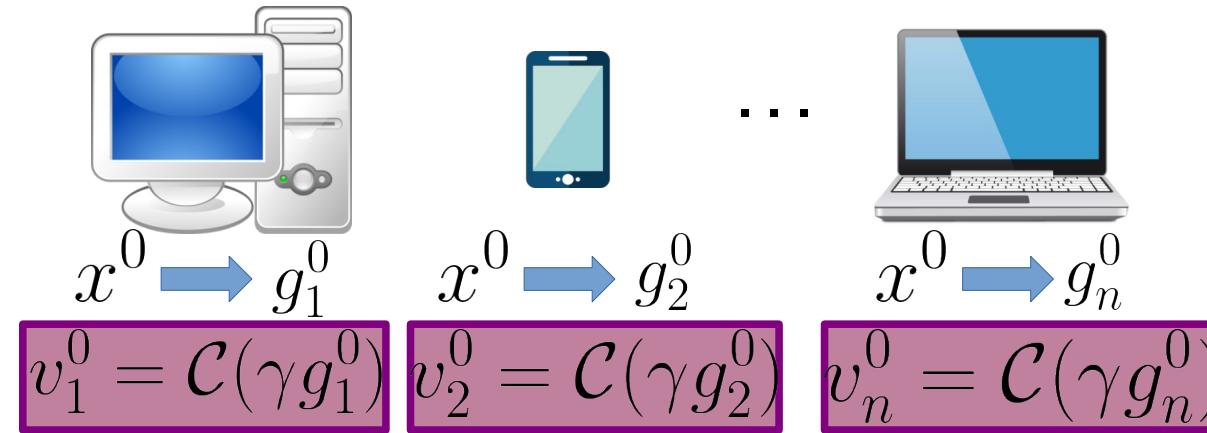
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 $x^0$ 

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 $x^0$ 

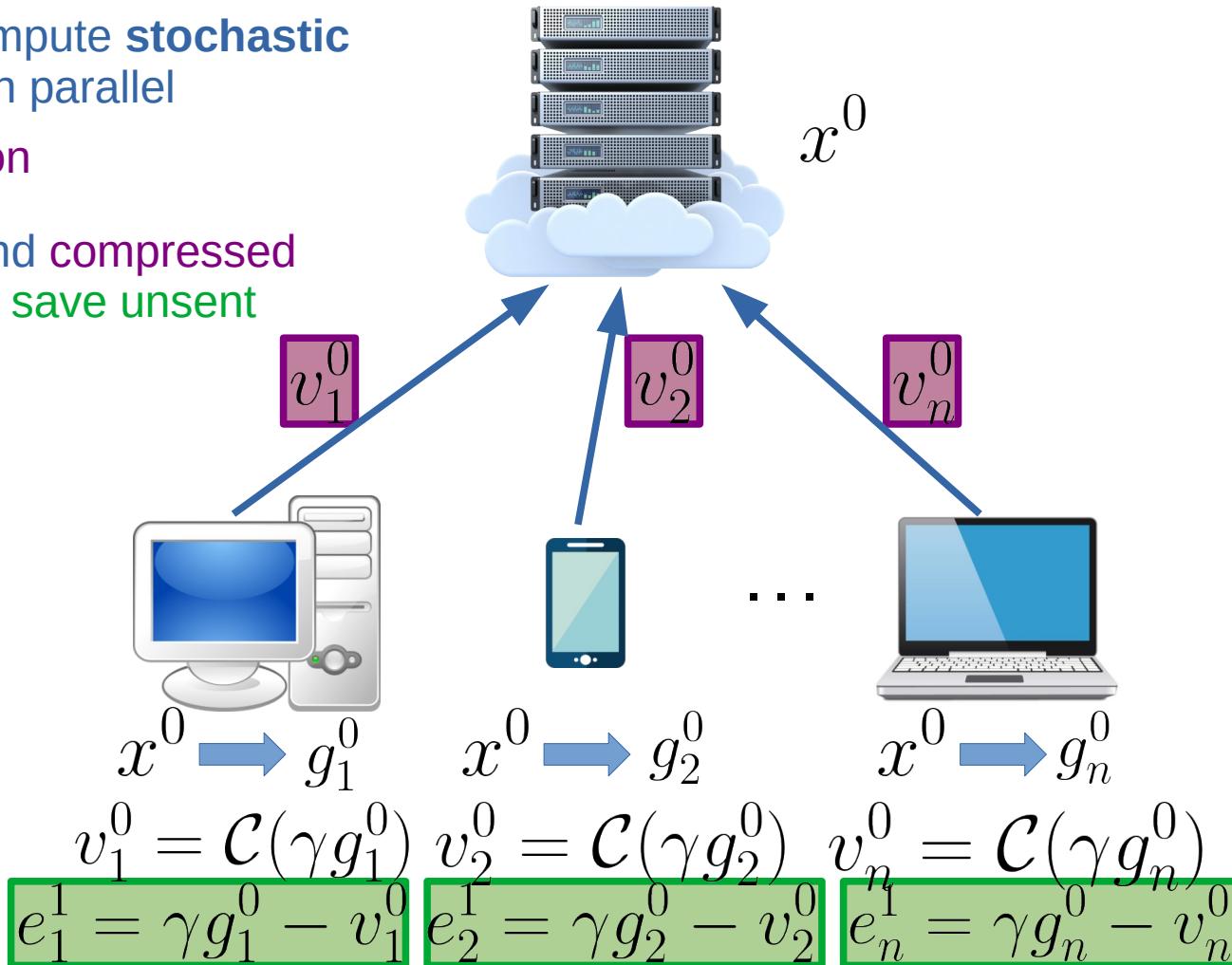
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2 Devices compute **stochastic gradients** in parallel

3 Compression

4 Devices send compressed vectors and save unsent information



# Step 1

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- 2 Devices compute **stochastic gradients** in parallel
- 3 Compression
- 4 Devices send **compressed vectors** and **save unsent information**
- 5 Server gathers the information and updates the parameters



$$x^0 \rightarrow x^1 = x^0 - \frac{1}{n} \sum_{i=1}^n v_i^0$$



$$x^0 \rightarrow g_1^0$$



$$x^0 \rightarrow g_2^0$$

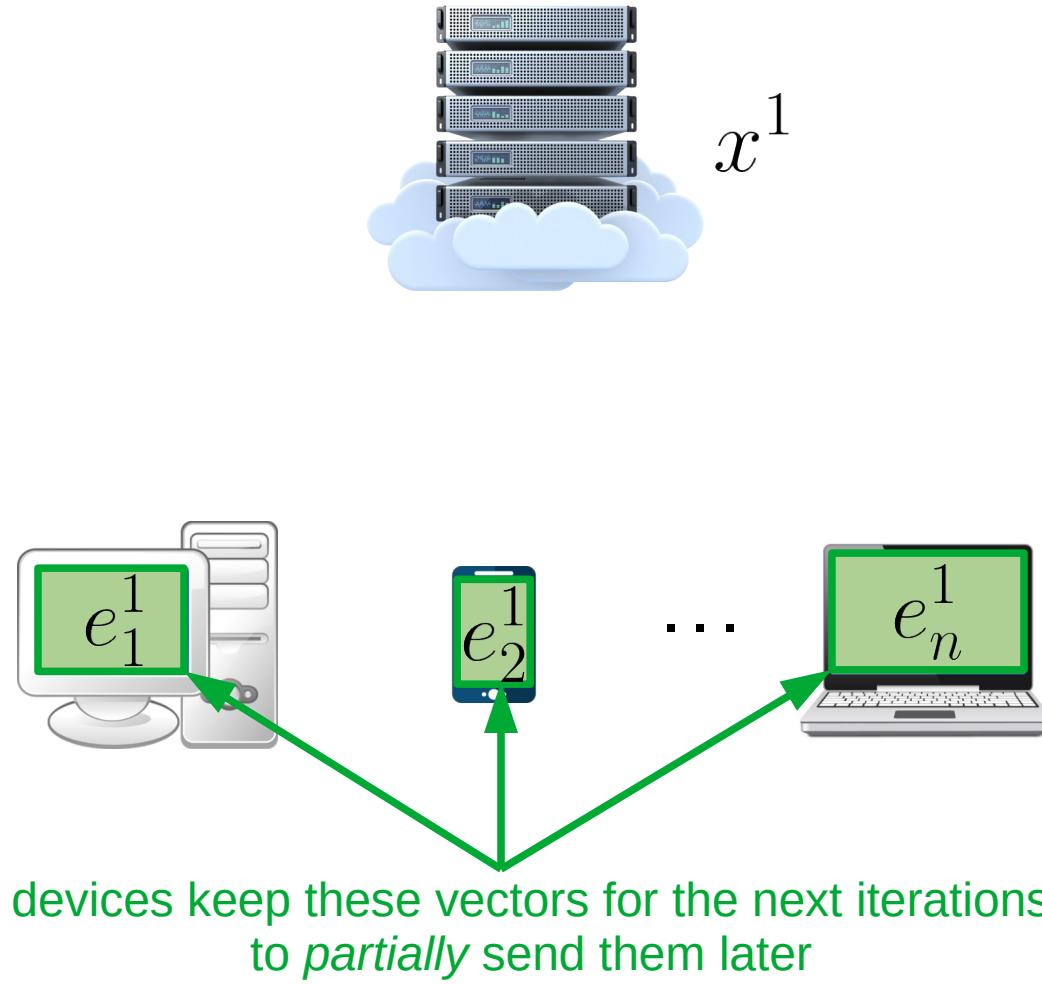
...



$$x^0 \rightarrow g_n^0$$

$$\begin{aligned} v_1^0 &= \mathcal{C}(\gamma g_1^0) & v_2^0 &= \mathcal{C}(\gamma g_2^0) & v_n^0 &= \mathcal{C}(\gamma g_n^0) \\ e_1^1 &= \gamma g_1^0 - v_1^0 & e_2^1 &= \gamma g_2^0 - v_2^0 & e_n^1 &= \gamma g_n^0 - v_n^0 \end{aligned}$$

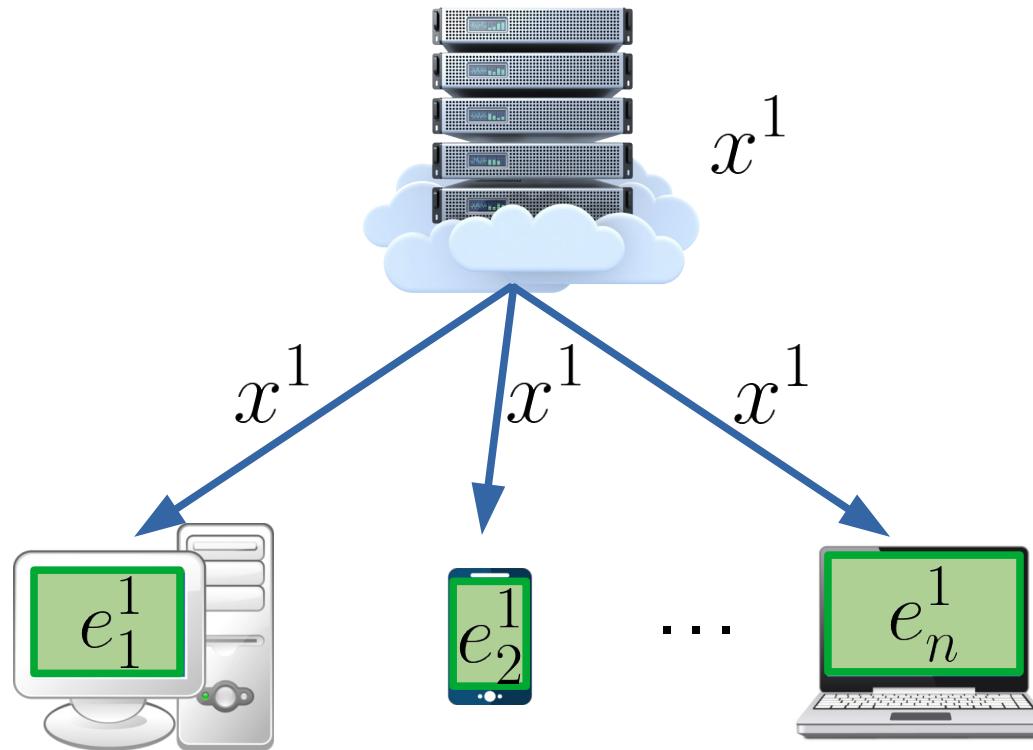
# Step 1



1

Server broadcasts new parameters

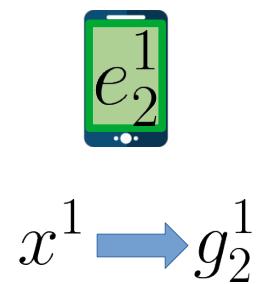
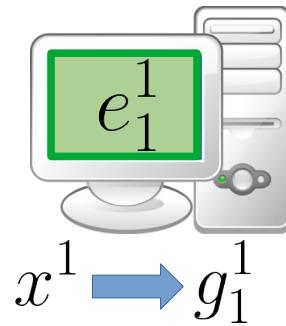
## Step 2



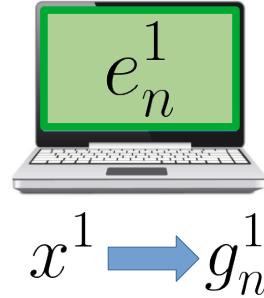
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1 Server broadcasts new parameters

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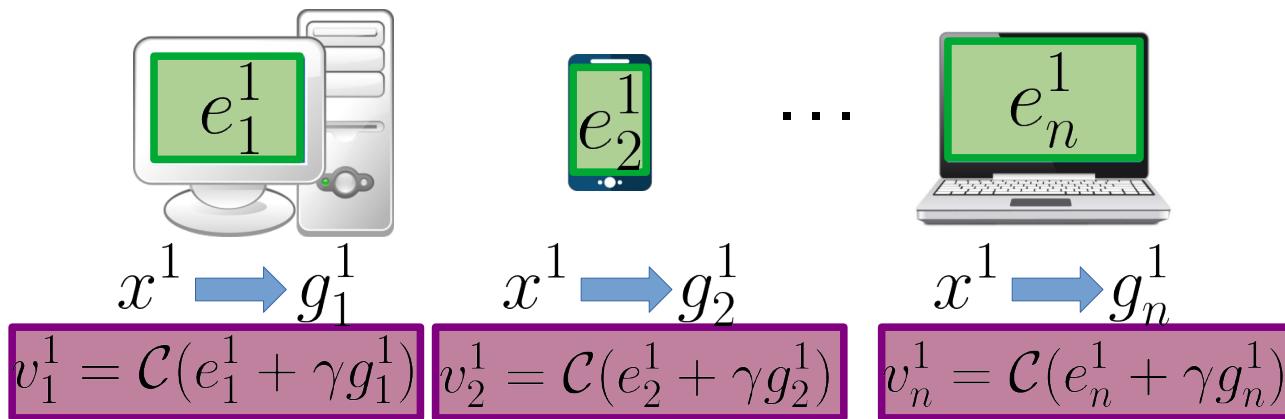


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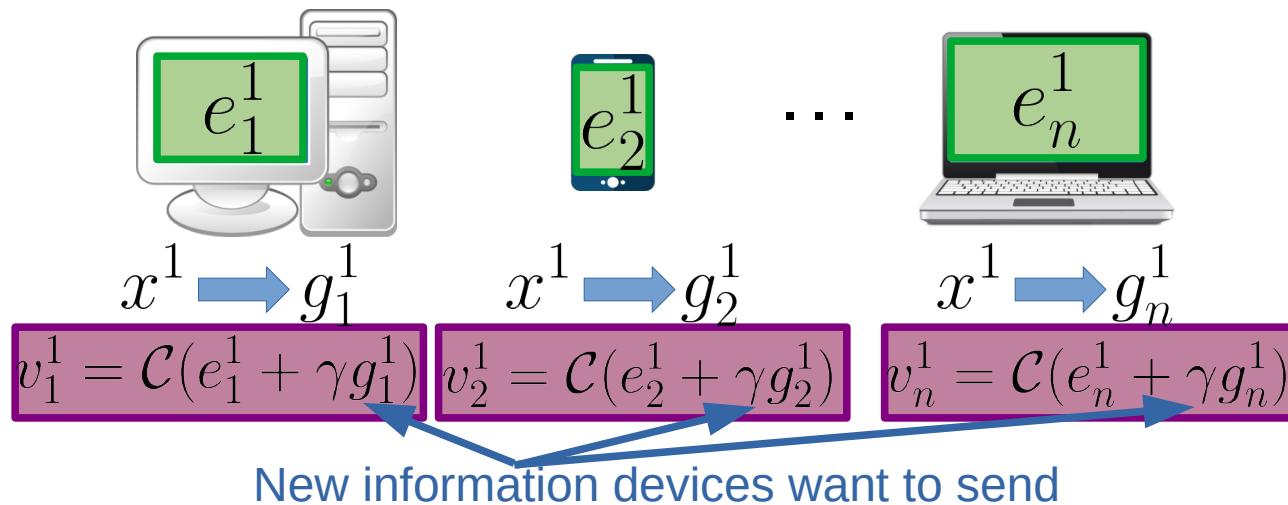
# Step 2

- 1 Server broadcasts new parameters
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- 3 Compression



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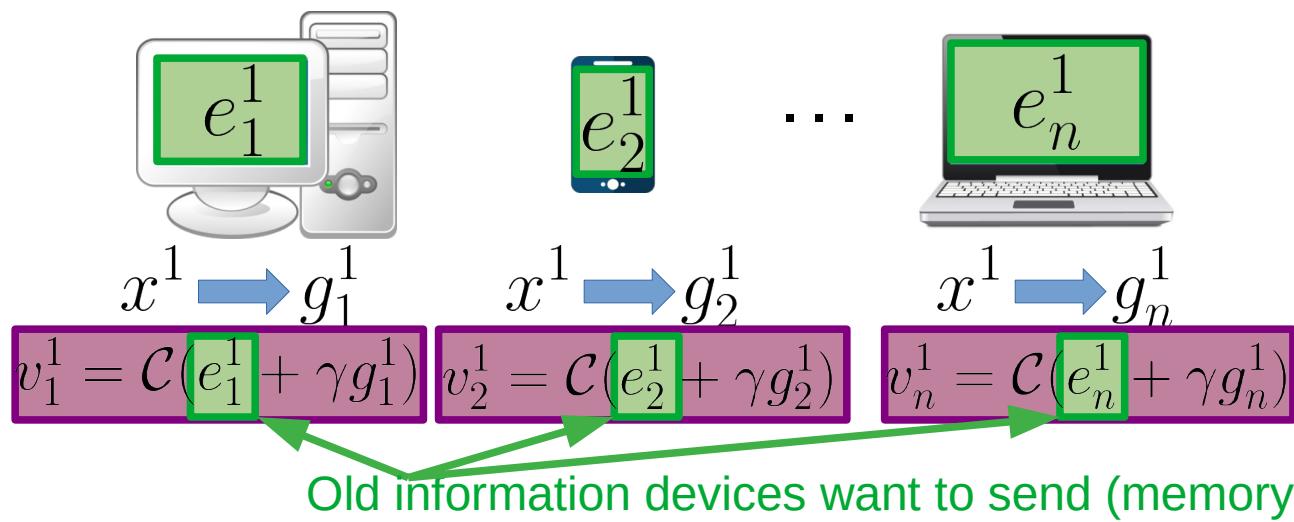


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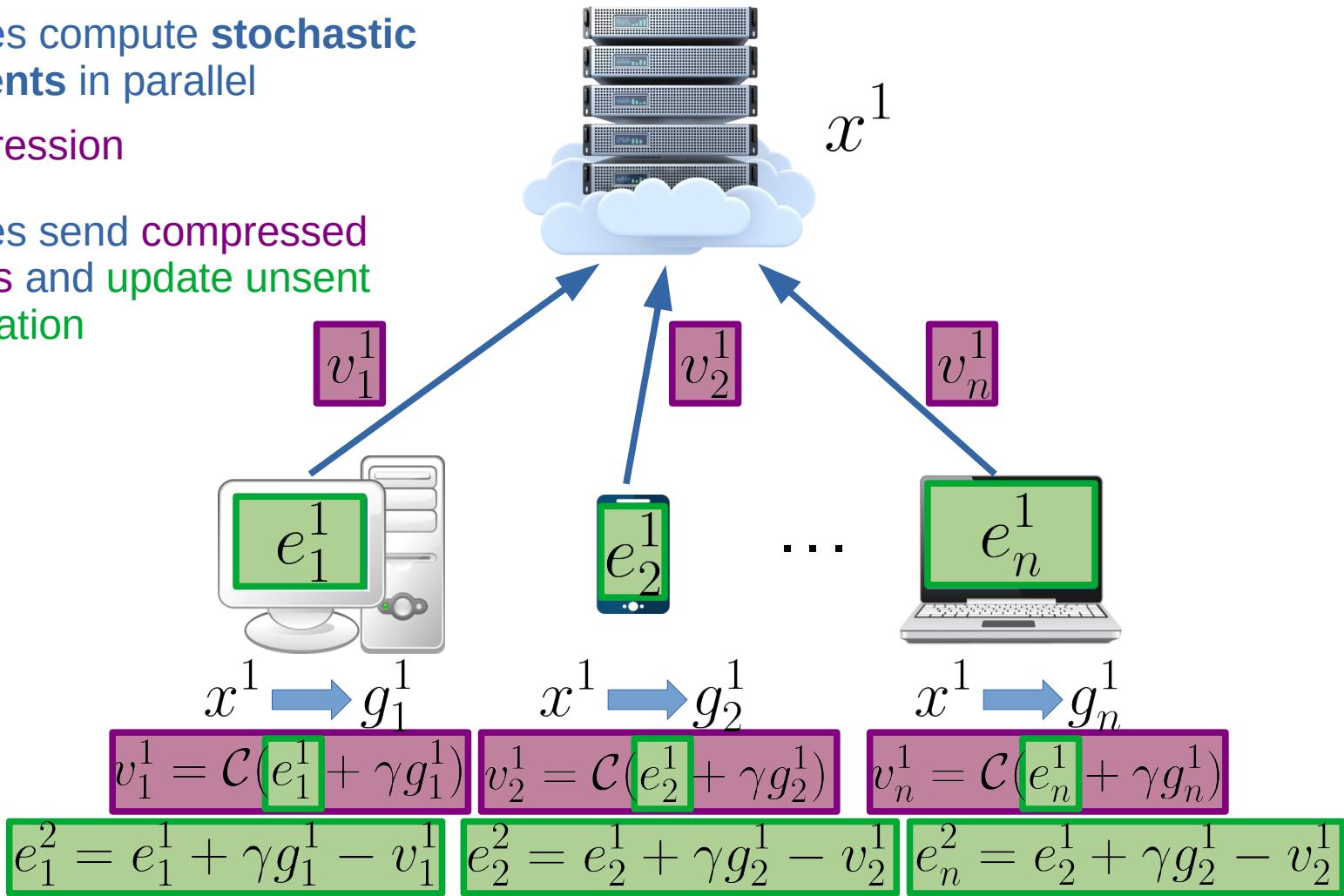


$x^1$



# Step 2

- 1 Server broadcasts new parameters
- 2 Devices compute **stochastic gradients** in parallel
- 3 Compression
- 4 Devices send compressed vectors and update unsent information

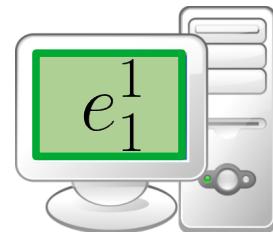


# Step 2

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- 4 Devices send **compressed vectors** and **update unsent information**
- 5 Server gathers the information and updates the parameters

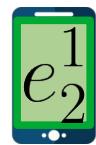


$$x^1 \rightarrow x^2 = x^1 - \frac{1}{n} \sum_{i=1}^n v_i^1$$



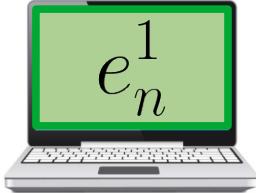
$$x^1 \rightarrow g_1^1$$

$$v_1^1 = \mathcal{C}(e_1^1 + \gamma g_1^1) \quad v_2^1 = \mathcal{C}(e_2^1 + \gamma g_2^1) \quad v_n^1 = \mathcal{C}(e_n^1 + \gamma g_n^1)$$



$$x^1 \rightarrow g_2^1$$

...



$$x^1 \rightarrow g_n^1$$

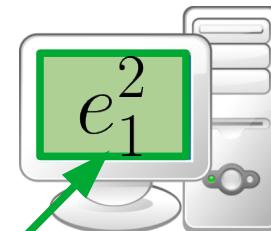
$$e_1^2 = e_1^1 + \gamma g_1^1 - v_1^1 \quad e_2^2 = e_2^1 + \gamma g_2^1 - v_2^1 \quad e_n^2 = e_n^1 + \gamma g_n^1 - v_2^1$$

# Step 2

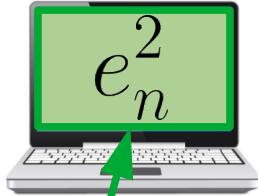
- 1 Server broadcasts new parameters
- 2 Devices compute **stochastic gradients** in parallel
- 3 Compression
- 4 Devices send **compressed vectors** and update unsent information
- 5 Server gathers the information and updates the parameters
- 6 Devices update their memory



$$x^1 \rightarrow x^2 = x^1 - \frac{1}{n} \sum_{i=1}^n v_i^1$$



...



$$e_1^2 = e_1^1 + \gamma g_1^1 - v_1^1$$

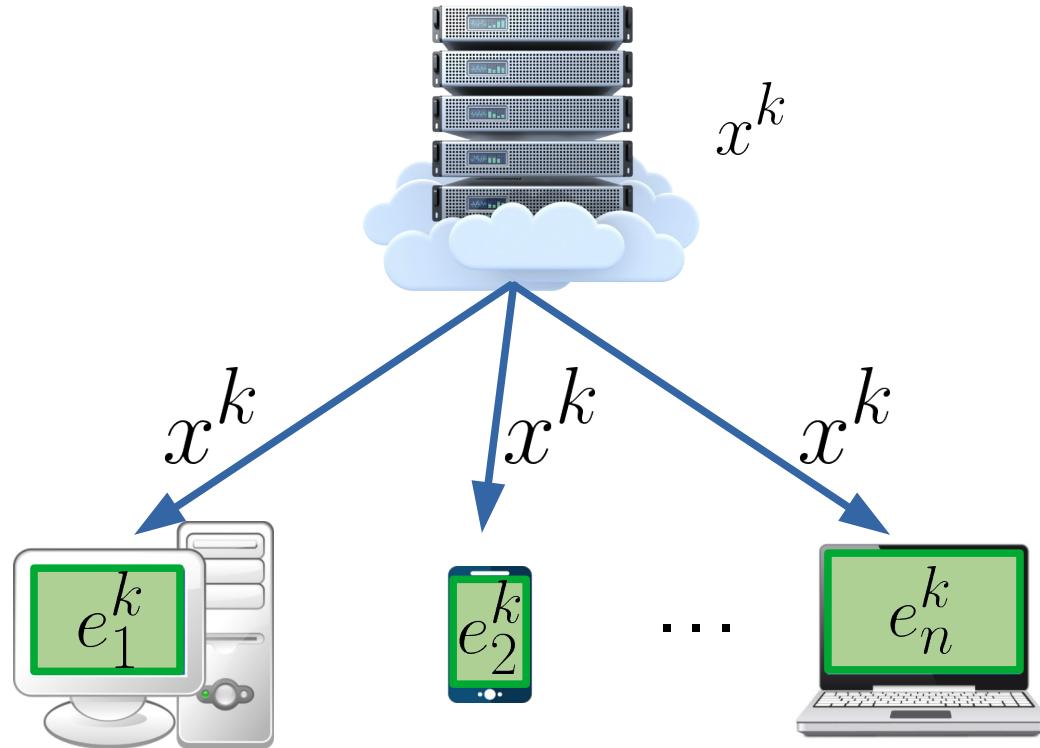
$$e_2^2 = e_2^1 + \gamma g_2^1 - v_2^1$$

$$e_n^2 = e_2^1 + \gamma g_2^1 - v_2^1$$

1

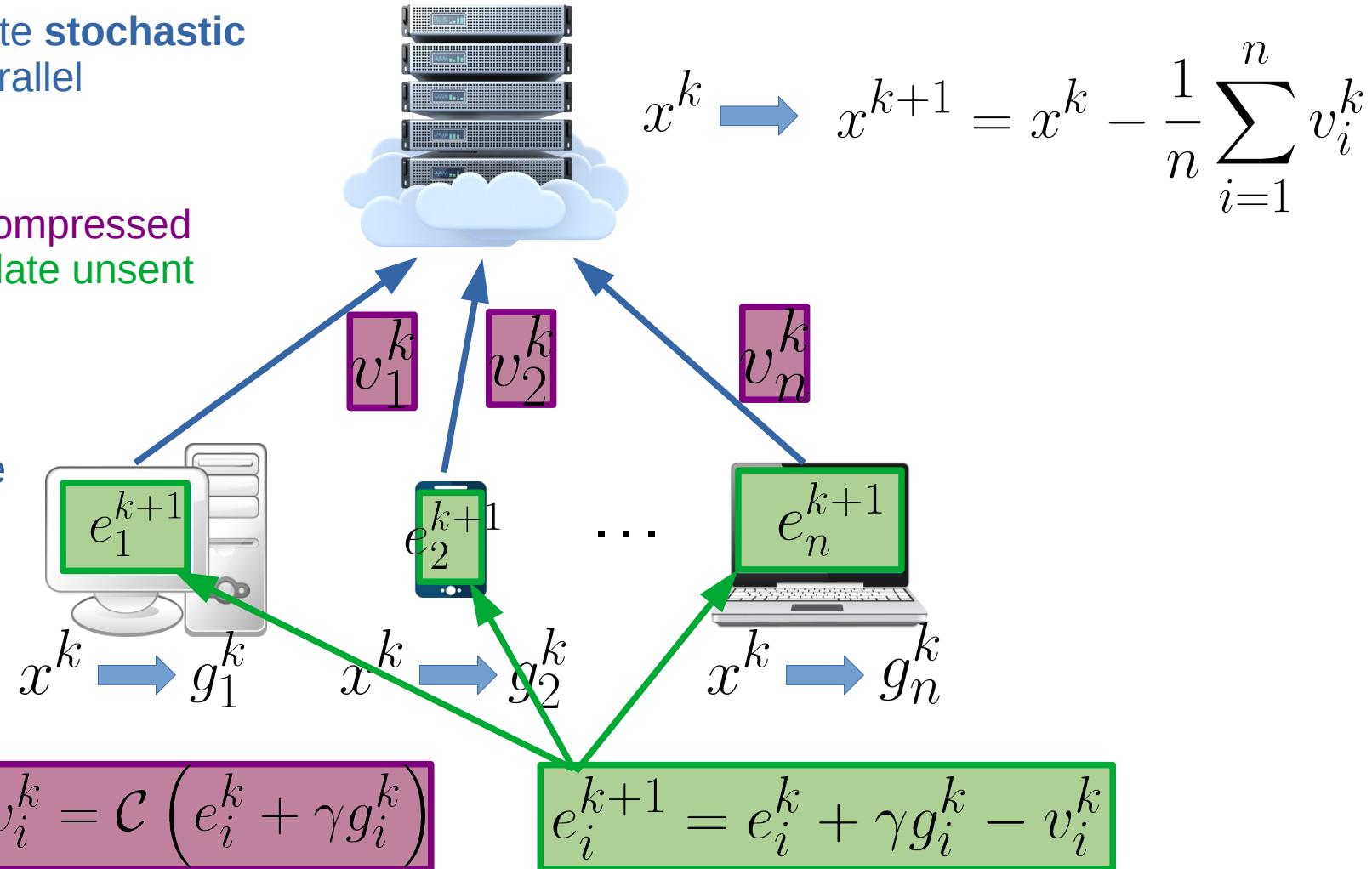
Server broadcasts new parameters

# Step k+1



# Step $k+1$

- 1 Server broadcasts new parameters
- 2 Workers compute **stochastic gradients** in parallel
- 3 Compression
- 4 Devices send compressed vectors and update unsent information
- 5 Server gathers the information and updates the parameters
- 6 Repeat steps 1 – 5



# Error-Compensated SGD



Converges even with biased compression operators

EC-SGD finds such  $\hat{x}$  that  $\mathbb{E}[f(\hat{x})] - f(x^*) \leq \varepsilon$  after

Hides logarithmical  
factors

$$\tilde{\mathcal{O}}\left(\frac{L}{\delta\mu} + \frac{\sigma^2}{n\mu\varepsilon} + \frac{\sqrt{L(\sigma^2 + \zeta_*^2/\delta)}}{\mu\sqrt{\delta\varepsilon}}\right)$$

iterations

$$\mathbb{E}\|\mathcal{C}(x) - x\|^2 \leq (1 - \delta)\|x\|^2$$

$$\mathbb{E} \left[ \|g_i^k - \nabla f_i(x^k)\|^2 \mid x^k \right] \leq \sigma^2$$

$$\zeta_*^2 = \frac{1}{n} \sum_{i=1}^n \|\nabla f_i(x^*)\|^2$$

# Error-Compensated SGD



Converges even with biased compression operators



Fails to converge with **linear rate** even when workers compute full gradients

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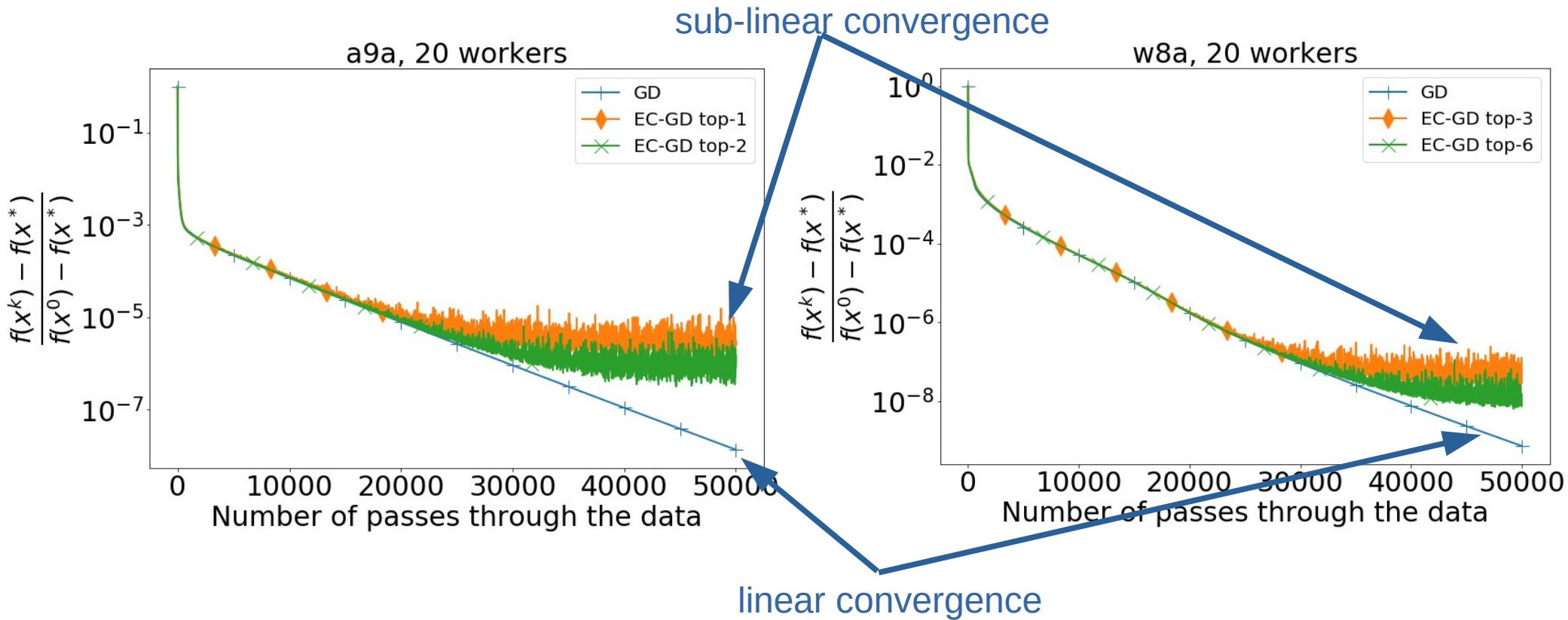
$$\tilde{\mathcal{O}}\left(\frac{L}{\delta\mu} + \frac{\sigma^2}{n\mu\varepsilon} + \frac{\sqrt{L(\sigma^2 + \zeta_*^2/\delta)}}{\mu\sqrt{\delta\varepsilon}}\right) \text{ iterations}$$

$$\mathbb{E}\|\mathcal{C}(x) - x\|^2 \leq (1 - \delta)\|x\|^2 \quad \mathbb{E}\left[\|g_i^k - \nabla f_i(x^k)\|^2 \mid x^k\right] \leq \sigma^2$$

$$\zeta_*^2 = \frac{1}{n} \sum_{i=1}^n \|\nabla f_i(x^*)\|^2$$

# EC-GD and Logistic Regression

$$\min_{x \in \mathbb{R}^d} \left\{ f(x) = \frac{1}{N} \sum_{i=1}^N \log (1 + \exp (-y_i \cdot (Ax)_i)) + \frac{\mu}{2} \|x\|^2 \right\}$$



# Error-Compensated SGD



Converges even with biased compression operators



Fails to converge with **linear rate** even when workers compute full gradients

Questions:

- 1 *Is it possible to design **linearly converging SGD** with error compensation when workers compute full gradients, i.e., linearly converging **EC-GD**?*
- 2 *Is it possible to design **linearly converging SGD** with error compensation when **the local loss functions have a finite-sum form**?*

The answer is Yes for both questions

## 5.1. New method: EC-GDstar

# Error-Compensated GD

EC-GD finds such  $\hat{x}$  that  $\mathbb{E}[f(\hat{x})] - f(x^*) \leq \varepsilon$  after

Hides logarithmical factors   $\tilde{\mathcal{O}}\left(\frac{L}{\delta\mu} + \frac{\sqrt{L}\zeta_*^2}{\mu\delta\sqrt{\varepsilon}}\right)$  iterations

$$\zeta_*^2 = \frac{1}{n} \sum_{i=1}^n \|\nabla f_i(x^*)\|^2$$

# Error-Compensated GD

EC-GD finds such  $\hat{x}$  that  $\mathbb{E}[f(\hat{x})] - f(x^*) \leq \varepsilon$  after

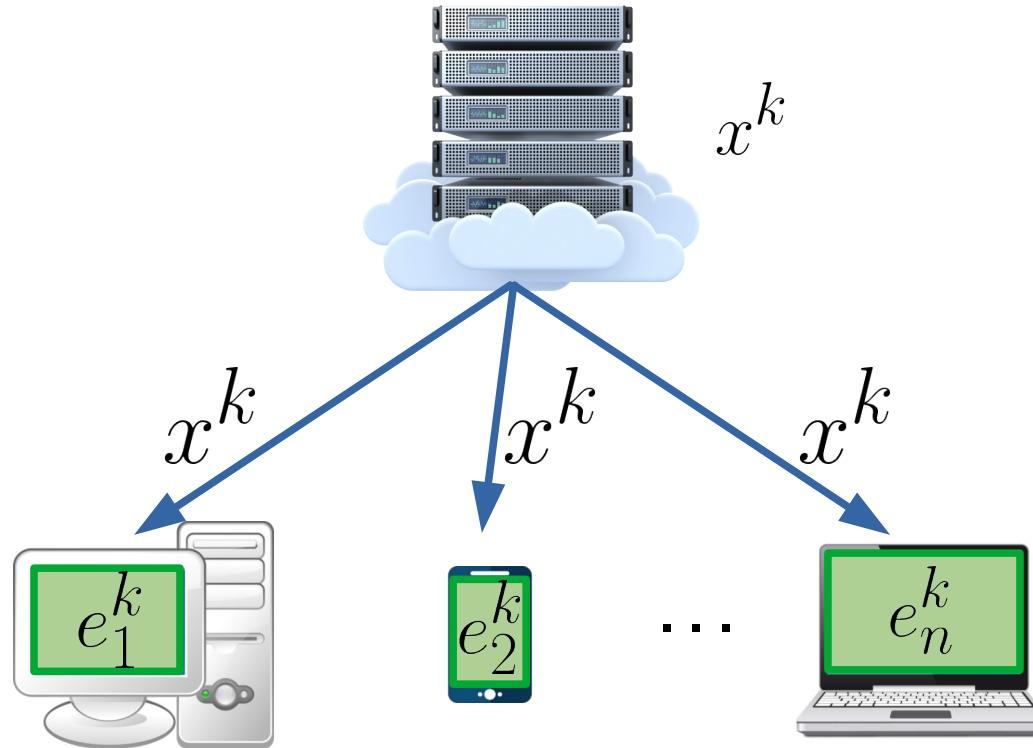
Hides logarithmical factors  $\longrightarrow \tilde{\mathcal{O}}\left(\frac{L}{\delta\mu} + \frac{\sqrt{L}\zeta_*^2}{\mu\delta\sqrt{\varepsilon}}\right)$  iterations

$$\zeta_*^2 = \frac{1}{n} \sum_{i=1}^n \|\nabla f_i(x^*)\|^2$$

What if devices know these vectors from the beginning?

# EC-GDstar

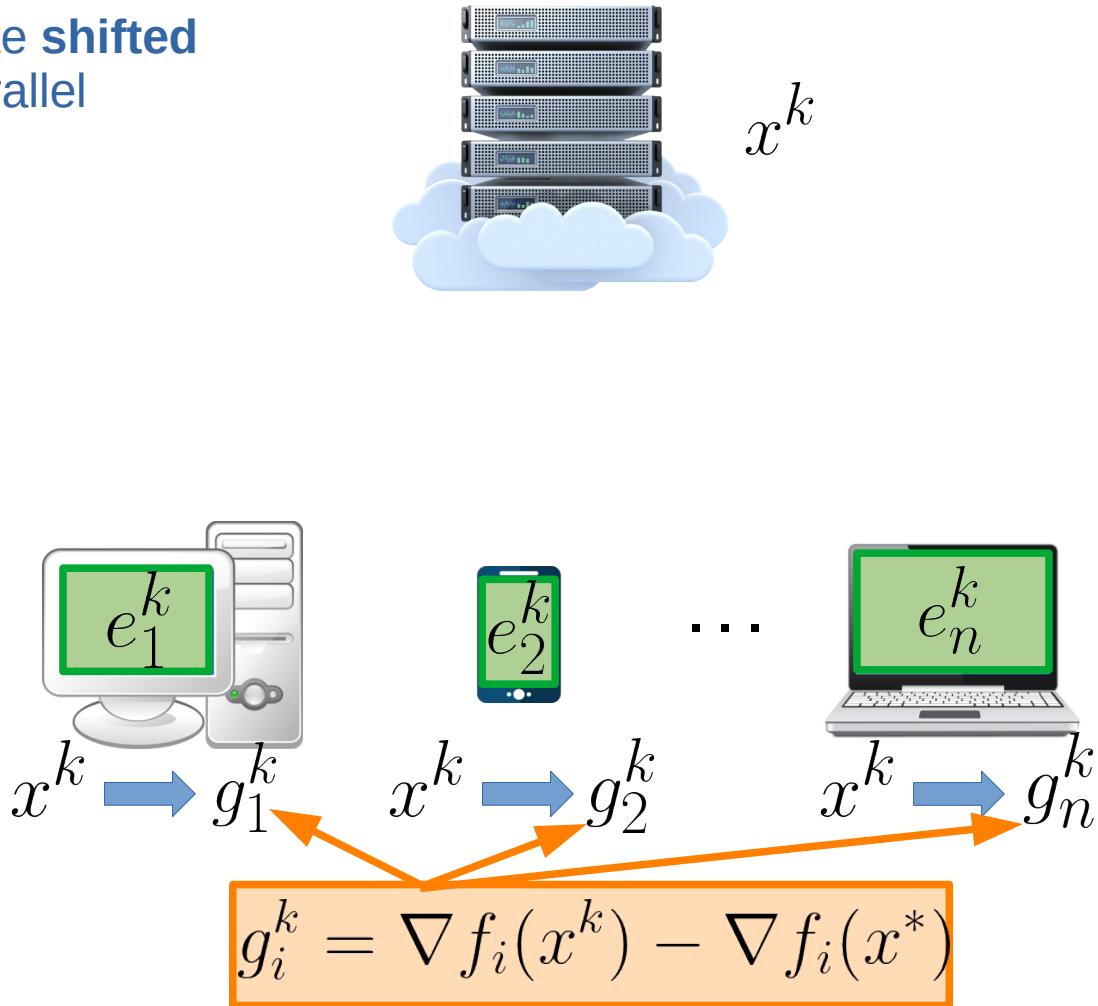
Server broadcasts new parameters



# EC-GDstar

1 Server broadcasts new parameters

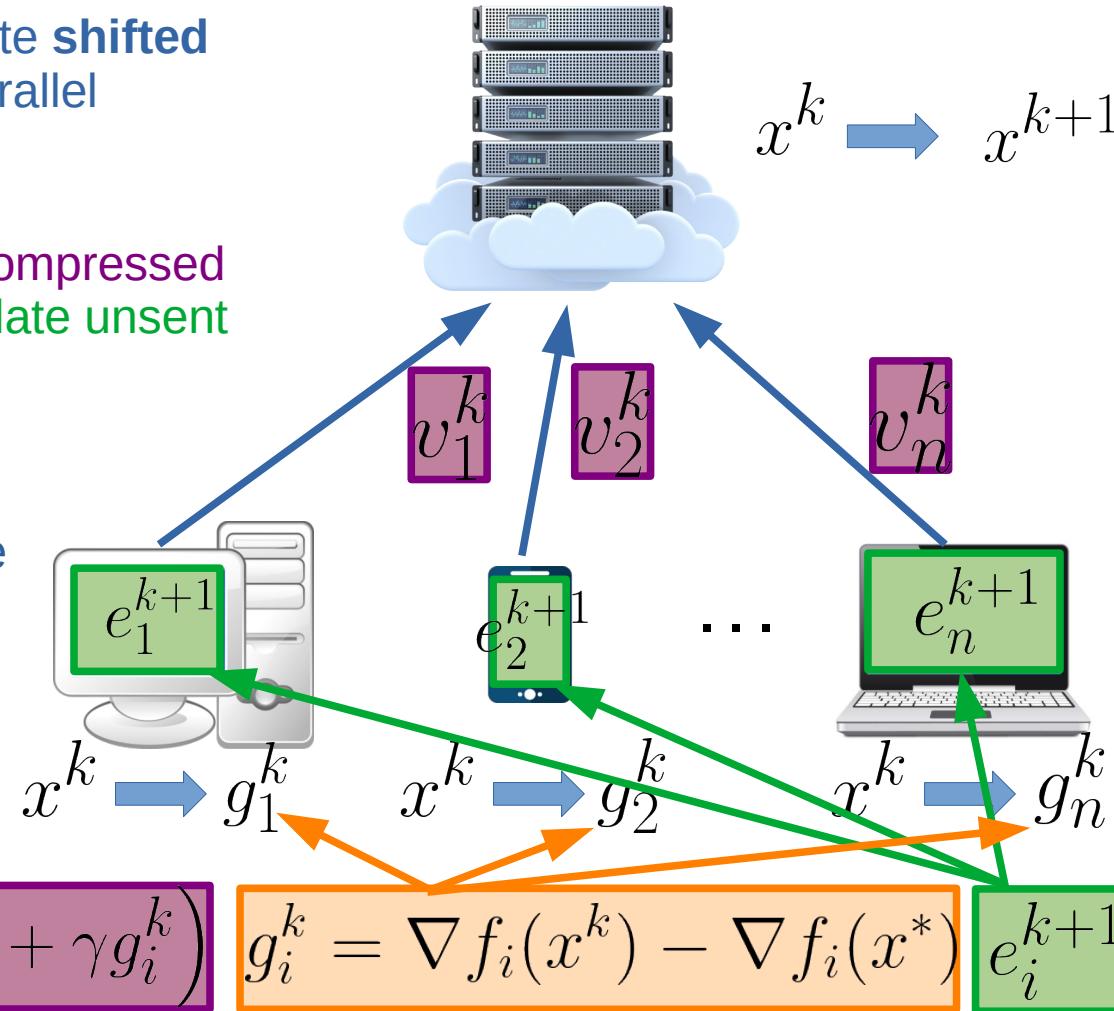
2 Workers compute **shifted gradients** in parallel



# EC-GDstar

- 1 Server broadcasts new parameters
- 2 Workers compute **shifted gradients** in parallel
- 3 Compression
- 4 Devices send compressed vectors and update unsent information
- 5 Server gathers the information and updates the parameters
- 6 Repeat steps 1 – 5

$$x^k \rightarrow x^{k+1} = x^k - \frac{1}{n} \sum_{i=1}^n v_i^k$$



# EC-GDstar: Rate of Convergence

EC-GDstar finds such  $\hat{x}$  that  $\mathbb{E}[f(\hat{x})] - f(x^*) \leq \varepsilon$  after

$$\mathcal{O}\left(\frac{L}{\delta\mu} \ln \frac{1}{\varepsilon}\right) \text{ iterations}$$



Linear rate



The method is impractical: it uses the gradients at the solution

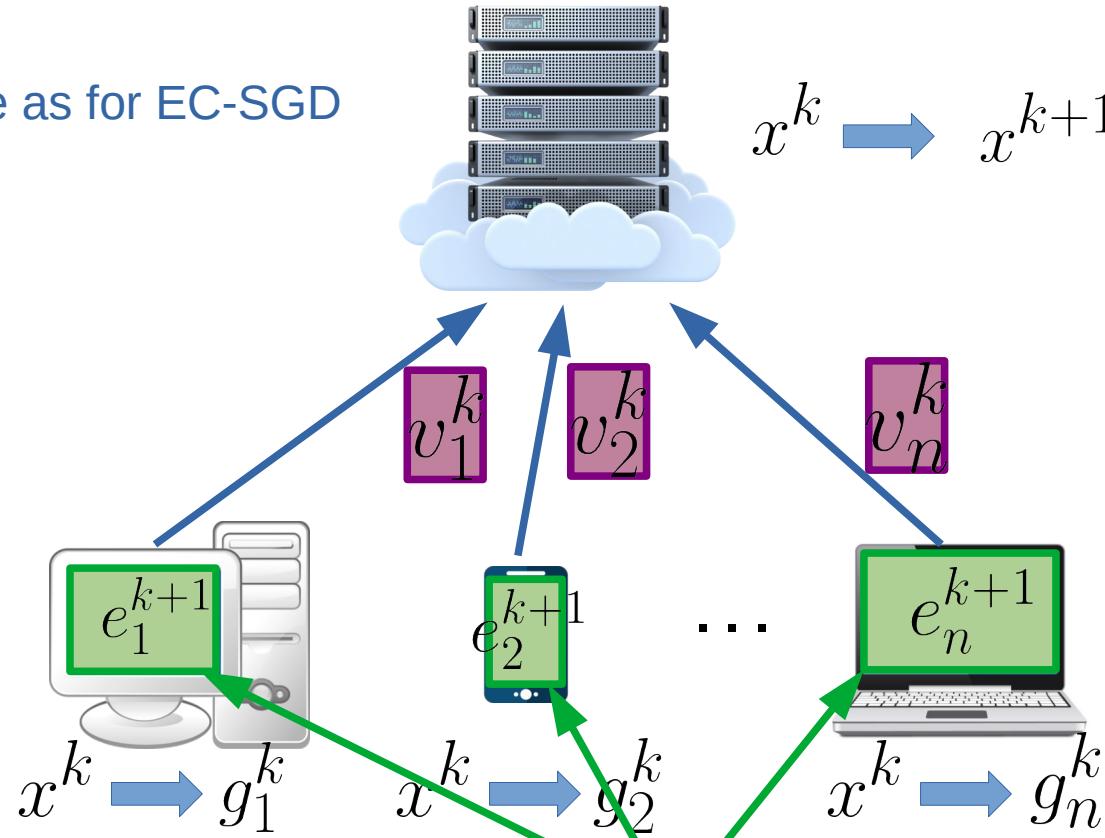
Can we develop a practical analog?

## 5.2. New method: EC-SGD-DIANA

# EC-SGD-DIANA

The same scheme as for EC-SGD

$$x^k \rightarrow x^{k+1} = x^k - \frac{1}{n} \sum_{i=1}^n v_i^k$$

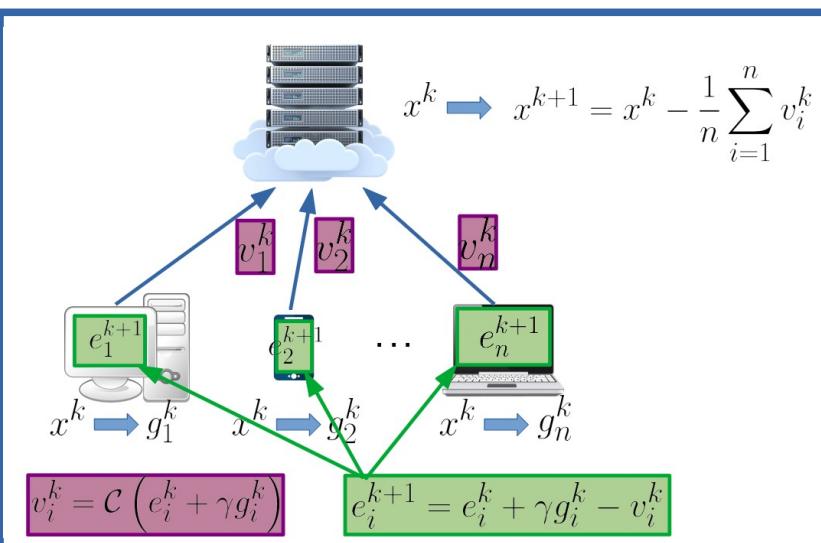


$$v_i^k = \mathcal{C} \left( e_i^k + \gamma g_i^k \right)$$

$$e_i^{k+1} = e_i^k + \gamma g_i^k - v_i^k$$

# EC-SGD-DIANA

$$g_i^k = \hat{g}_i^k - h_i^k + h^k$$

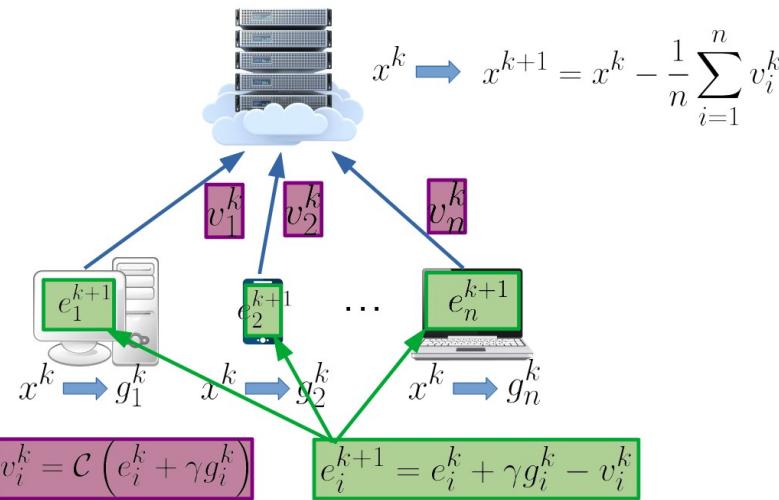


# EC-SGD-DIANA

The key insight why do we need  $\{h_i^k\}_{i=1}^n$ :

it reduces the variance coming from compressions via learning the gradients at the solution!

$$\mathbb{E} [\hat{g}_i^k \mid x^k] = \nabla f_i(x^k)$$



$$g_i^k = \hat{g}_i^k - h_i^k + h^k$$

$$h^k = \frac{1}{n} \sum_{i=1}^n h_i^k$$

stepsize

$$h_i^{k+1} = h_i^k + \alpha Q(\hat{g}_i^k - h_i^k)$$

Works for both cases:

●  $f_i(x) = \mathbb{E}_{\xi_i \sim \mathcal{D}_i} [f_{\xi_i}(x)]$

$$\hat{g}_i^k = \nabla f_{\xi_i}(x^k)$$

●  $f_i(x) = \frac{1}{m} \sum_{j=1}^m f_{ij}(x)$

$$\hat{g}_i^k = \nabla f_{il}(x^k)$$

$l \sim [m]$  uniformly at random

Server broadcasts this vector to the workers

Workers send these vectors to the server

# EC-SGD-DIANA: Rate of Convergence

EC-SGD-DIANA finds such  $\hat{x}$  that  $\mathbb{E}[f(\hat{x})] - f(x^*) \leq \varepsilon$  after

Hides logarithmical factors

iterations

Option I:  $\tilde{\mathcal{O}} \left( \omega + \frac{L}{\delta\mu} + \frac{\sigma^2}{n\mu\varepsilon} + \frac{\sqrt{L\sigma^2}}{\delta\mu\sqrt{\varepsilon}} \right)$

Option II:  $\tilde{\mathcal{O}} \left( \frac{1+\omega}{\delta} + \frac{L}{\delta\mu} + \frac{\sigma^2}{n\mu\varepsilon} + \frac{\sqrt{L\sigma^2}}{\mu\sqrt{\delta\varepsilon}} \right)$

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Hides logarithmical factors

iterations

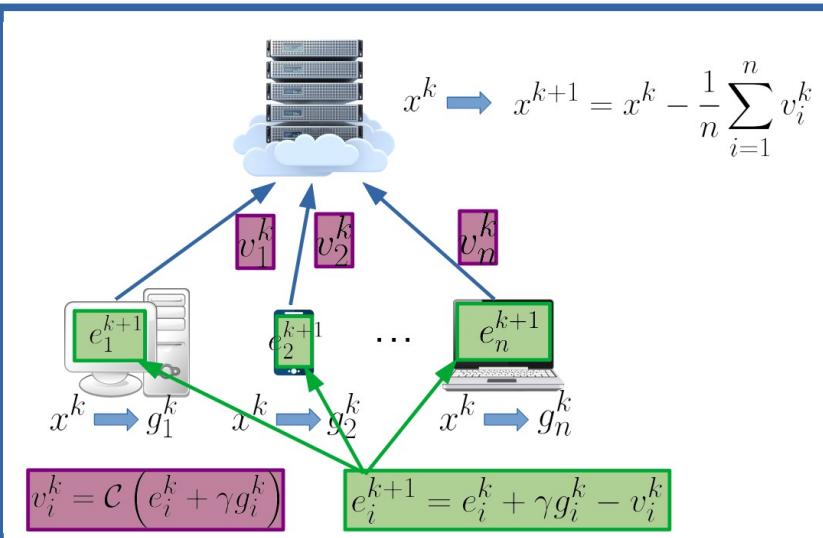
Moreover, if workers compute **full gradients**, then the rate of convergence is linear

$$\mathcal{O} \left( \left( \omega + \frac{L}{\delta\mu} \right) \log \frac{1}{\varepsilon} \right)$$

## 5.3. New method: EC-LSVRG-DIANA

# EC-LSVRG-DIANA

$$g_i^k = \hat{g}_i^k - h_i^k + h^k$$



Works for the case:

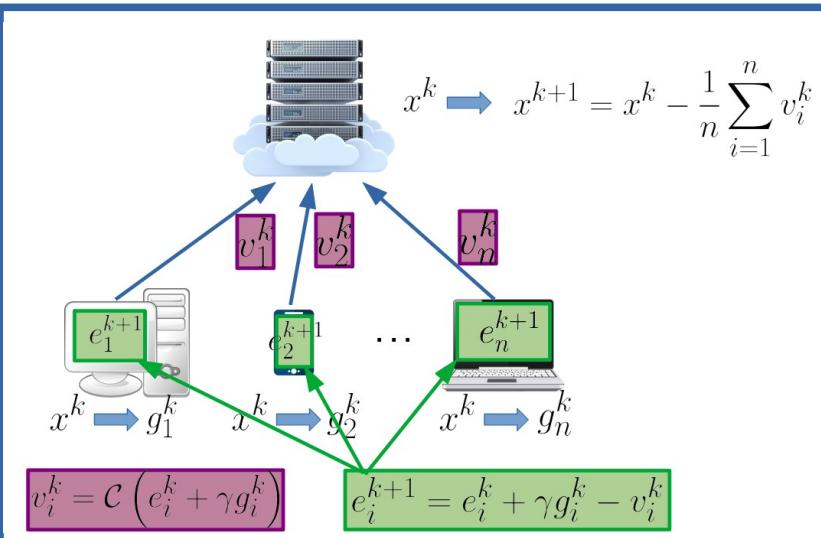
●

$$f_i(x) = \frac{1}{m} \sum_{j=1}^m f_{ij}(x)$$

# EC-LSVRG-DIANA

$$g_i^k = \hat{g}_i^k - h_i^k + h^k \quad l \sim [m] \text{ uniformly at random}$$

$$\hat{g}_i^k = \nabla f_{il}(x^k) - \nabla f_{il}(w_i^k) + \nabla f_i(w_i^k)$$



Works for the case:

●  $f_i(x) = \frac{1}{m} \sum_{j=1}^m f_{ij}(x)$

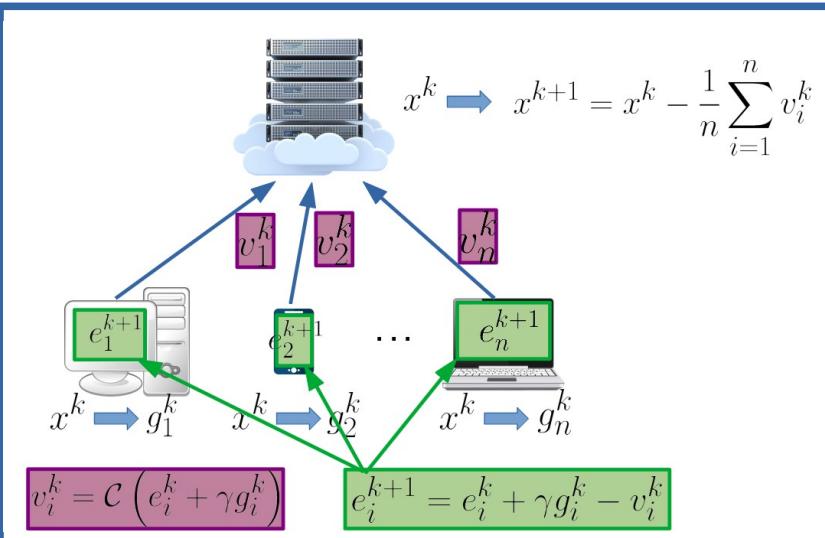
# EC-LSVRG-DIANA

$$g_i^k = \hat{g}_i^k - h_i^k + h^k \quad l \sim [m] \text{ uniformly at random}$$

$$\hat{g}_i^k = \nabla f_{il} \left( x^k \right) - \nabla f_{il} \left( w_i^k \right) + \nabla f_i \left( w_i^k \right)$$

Reduction of the variance introduced due to the stochasticity of the gradients

$$w_i^{k+1} = \begin{cases} x^k, & \text{with probability } p \\ w_i^k, & \text{with probability } 1 - p \end{cases}$$



Works for the case:

●  $f_i(x) = \frac{1}{m} \sum_{j=1}^m f_{ij}(x)$

# EC-LSVRG-DIANA: Rate of Convergence

EC-LSVRG-DIANA finds such  $\hat{x}$  that  $\mathbb{E}[f(\hat{x})] - f(x^*) \leq \varepsilon$  after

$$\mathcal{O}\left(\left(\omega + m + \frac{L}{\delta\mu}\right) \log \frac{1}{\epsilon}\right) \text{ iterations}$$

# 6. Unified Convergence Analysis of Methods with Error Compensation

# Key Assumption

$$g^k = \frac{1}{n} \sum_{i=1}^n g_i^k, \quad \mathbb{E} [g^k | x^k] = \nabla f(x^k) \quad \bar{g}_i^k = \mathbb{E} [g_i^k | x^k]$$

$$\frac{1}{n} \sum_{i=1}^n \|\bar{g}_i^k\|^2 \leq 2A(f(x^k) - f(x^*)) + B_1 \sigma_{1,k}^2 + B_2 \sigma_{2,k}^2 + D_1$$

$$\frac{1}{n} \sum_{i=1}^n \mathbb{E} [\|g_i^k - \bar{g}_i^k\|^2 | x^k] \leq 2\tilde{A}(f(x^k) - f(x^*)) + \tilde{B}_1 \sigma_{1,k}^2 + \tilde{B}_2 \sigma_{2,k}^2 + \tilde{D}_1$$

$$\mathbb{E} [\|g^k\|^2 | x^k] \leq 2A'(f(x^k) - f(x^*)) + B'_1 \sigma_{1,k}^2 + B'_2 \sigma_{2,k}^2 + D'_1$$

$$\mathbb{E} [\sigma_{1,k+1}^2 | \sigma_{1,k}^2, \sigma_{2,k}^2] \leq (1 - \rho_1) \sigma_{1,k}^2 + 2C_1(f(x^k) - f(x^*)) + G\rho_1 \sigma_{2,k}^2 + D_2$$

$$\mathbb{E} [\sigma_{2,k+1}^2 | \sigma_{2,k}^2] \leq (1 - \rho_2) \sigma_{2,k}^2 + 2C_2(f(x^k) - f(x^*))$$

# Key Assumption

$$g^k = \frac{1}{n} \sum_{i=1}^n g_i^k, \quad \mathbb{E} [g^k | x^k] = \nabla f(x^k) \quad \bar{g}_i^k = \mathbb{E} [g_i^k | x^k]$$

$$\frac{1}{n} \sum_{i=1}^n \|\bar{g}_i^k\|^2 \leq 2A(f(x^k) - f(x^*)) + B_1\sigma_{1,k}^2 + B_2\sigma_{2,k}^2 + D_1$$

$$\frac{1}{n} \sum_{i=1}^n \mathbb{E} [\|g_i^k - \bar{g}_i^k\|^2 | x^k] \leq 2\tilde{A}(f(x^k) - f(x^*)) + \tilde{B}_1\sigma_{1,k}^2 + \tilde{B}_2\sigma_{2,k}^2 + \tilde{D}_1$$

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$$\mathbb{E} [\sigma_{1,k+1}^2 | \sigma_{1,k}^2, \sigma_{2,k}^2] \leq (1 - \rho_1) \sigma_{1,k}^2 + 2C_1(f(x^k) - f(x^*)) + G\rho_1\sigma_{2,k}^2 + D_2$$

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Reflects smoothness properties of the problem and noises introduced by compressions and stochastic gradients

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$$g^k = \frac{1}{n} \sum_{i=1}^n g_i^k, \quad \mathbb{E} [g^k | x^k] = \nabla f(x^k) \quad \bar{g}_i^k = \mathbb{E} [g_i^k | x^k]$$

$$\frac{1}{n} \sum_{i=1}^n \|\bar{g}_i^k\|^2 \leq 2A(f(x^k) - f(x^*)) + B_1\sigma_{1,k}^2 + B_2\sigma_{2,k}^2 + D_1$$

$$\frac{1}{n} \sum_{i=1}^n \mathbb{E} [\|g_i^k - \bar{g}_i^k\|^2 | x^k] \leq 2\tilde{A}(f(x^k) - f(x^*)) + \tilde{B}_1\sigma_{1,k}^2 + \tilde{B}_2\sigma_{2,k}^2 + \tilde{D}_1$$

$$\mathbb{E} [\|g^k\|^2 | x^k] \leq 2A'(f(x^k) - f(x^*)) + B'_1\sigma_{1,k}^2 + B'_2\sigma_{2,k}^2 + D'_1$$

$$\mathbb{E} [\sigma_{1,k+1}^2 | \sigma_{1,k}^2, \sigma_{2,k}^2] \leq (1 - \rho_1) \sigma_{1,k}^2 + 2C_1(f(x^k) - f(x^*)) + G\rho_1\sigma_{2,k}^2 + D_2$$

$$\mathbb{E} [\sigma_{2,k+1}^2 | \sigma_{2,k}^2] \leq (1 - \rho_2) \sigma_{2,k}^2 + 2C_2(f(x^k) - f(x^*))$$

  Reflects smoothness properties of the problem and noises introduced by compressions and stochastic gradients

  Describes the process of variance reduction of the variance coming from compressions

# Key Assumption

$$g^k = \frac{1}{n} \sum_{i=1}^n g_i^k, \quad \mathbb{E} [g^k | x^k] = \nabla f(x^k) \quad \bar{g}_i^k = \mathbb{E} [g_i^k | x^k]$$

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$$\frac{1}{n} \sum_{i=1}^n \mathbb{E} [\|g_i^k - \bar{g}_i^k\|^2 | x^k] \leq 2\tilde{A}(f(x^k) - f(x^*)) + \tilde{B}_1\sigma_{1,k}^2 + \tilde{B}_2\sigma_{2,k}^2 + \tilde{D}_1$$

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  Reflects smoothness properties of the problem and noises introduced by compressions and stochastic gradients

  Describes the process of variance reduction of the variance coming from compressions

  Describes the process of variance reduction of the variance coming from stochastic gradients

# Main Theorem

Some quantity depending only on the starting point and stepsize

$$\mathbb{E} [f(\bar{x}^K) - f(x^*)] \leq (1 - \eta)^K \frac{\Psi(x^0, \gamma)}{\gamma} + \gamma \Phi(D_1, \tilde{D}_1, D'_1, D_2)$$

$\eta = \min \left\{ \frac{\gamma\mu}{2}, \frac{\rho_1}{4}, \frac{\rho_2}{4} \right\}$

Linear function

```
graph TD; A["(1 - η)^K"] --> B["η = min { (γμ/2), (ρ₁/4), (ρ₂/4) }"]; C["Ψ(x⁰, γ)/γ"] --> D["γΦ(D₁, D₂)"]; D --> E["Linear function"]
```

# Methods with Error Compensation Covered by Our Framework

Problem	Method	Alg #	Citation	Sec #	Rate (constants ignored)
(1)+(3)	EC-SGDsr	Alg 3	new	H.1	$\tilde{\mathcal{O}}\left(\frac{\mathcal{L}}{\mu} + \frac{\sqrt{L\mathcal{L}}}{\delta\mu} + \frac{\text{Var}}{n\mu\varepsilon} + \frac{\sqrt{L(\text{Var}+\zeta_*^2/\delta)}}{\mu\sqrt{\delta\varepsilon}}\right)$
(1)+(2)	EC-SGD	Alg 4	[45]	H.2	$\tilde{\mathcal{O}}\left(\frac{\kappa}{\delta} + \frac{\text{Var}}{n\mu\varepsilon} + \frac{\sqrt{L(\text{Var}+\zeta_*^2/\delta)}}{\delta\mu\sqrt{\varepsilon}}\right)$
(1)+(3)	EC-GDstar	Alg 5	new	H.3	$\mathcal{O}\left(\frac{\kappa}{\delta} \log \frac{1}{\varepsilon}\right)$
(1)+(2)	EC-SGD-DIANA	Alg 6	new	H.4	Option I: $\tilde{\mathcal{O}}\left(\omega + \frac{\kappa}{\delta} + \frac{\sigma^2}{n\mu\varepsilon} + \frac{\sqrt{L\sigma^2}}{\delta\mu\sqrt{\varepsilon}}\right)$ Option II: $\tilde{\mathcal{O}}\left(\frac{1+\omega}{\delta} + \frac{\kappa}{\delta} + \frac{\sigma^2}{n\mu\varepsilon} + \frac{\sqrt{L\sigma^2}}{\mu\sqrt{\delta\varepsilon}}\right)$
(1)+(3)	EC-SGDsr-DIANA	Alg 7	new	H.5	Option I: $\tilde{\mathcal{O}}\left(\omega + \frac{\mathcal{L}}{\mu} + \frac{\sqrt{L\mathcal{L}}}{\delta\mu} + \frac{\text{Var}}{n\mu\varepsilon} + \frac{\sqrt{L\text{Var}}}{\delta\mu\sqrt{\varepsilon}}\right)$ Option II: $\tilde{\mathcal{O}}\left(\frac{1+\omega}{\delta} + \frac{\mathcal{L}}{\mu} + \frac{\sqrt{L\mathcal{L}}}{\delta\mu} + \frac{\text{Var}}{n\mu\varepsilon} + \frac{\sqrt{L\text{Var}}}{\mu\sqrt{\delta\varepsilon}}\right)$
(1)+(2)	EC-GD-DIANA <sup>†</sup>	Alg 6	new	H.4	$\mathcal{O}\left((\omega + \frac{\kappa}{\delta}) \log \frac{1}{\varepsilon}\right)$
(1)+(3)	EC-LSVRG	Alg 8	new	H.6	$\tilde{\mathcal{O}}\left(m + \frac{\kappa}{\delta} + \frac{\sqrt{L\zeta_*^2}}{\delta\mu\sqrt{\varepsilon}}\right)$
(1)+(3)	EC-LSVRGstar	Alg 9	new	H.7	$\mathcal{O}\left((m + \frac{\kappa}{\delta}) \log \frac{1}{\varepsilon}\right)$
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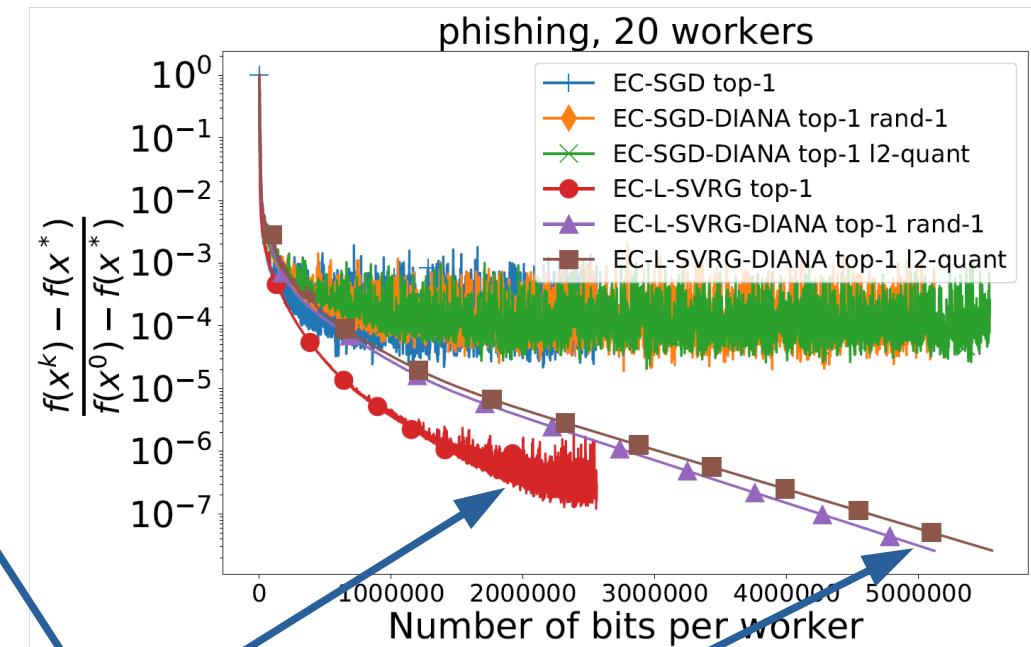
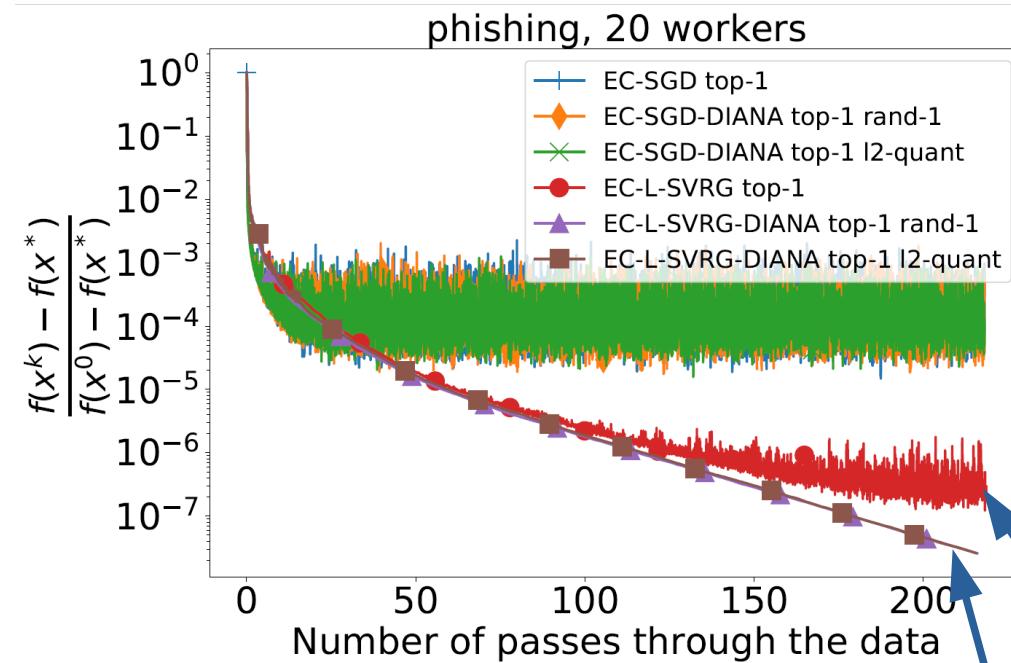
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Our framework covers even methods without error compensation and methods with delayed updates

# 7. Experiments

# Logistic Regression with L2-regularization



partial variance reduction

full variance reduction

# 8. More Methods

# More Methods Fitting our Framework

The generality of our approach helps to obtain convergence guarantees for a big number of different stochastic methods (even without error compensation). Here are some examples.

- Methods without error feedback: SGD, SGD-SR (arbitrary sampling), SAGA, SVRG, L-SVRG, QSGD, TernGrad, DQGD, DIANA, **DIANAsr-DQ**, VR-DIANA, JacSketch, SEGA
- Methods with delayed updates: D-SGD, **D-SGD-SR** (arbitrary sampling), **D-QSGD**, **D-SGD-DIANA**, **D-LSVRG**, **D-QLSVRG**, **D-LSVRG-DIANA**

# More Methods Fitting our Framework

The generality of our approach helps to obtain convergence guarantees for a big number of different stochastic methods (even without error compensation). Here are some examples.

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-  In one theorem, we recover the sharpest rates for all known special cases
-  16 new methods
-  Our analysis works for weakly convex objectives as well

Thank you for watching!

**bold font** = new method