

Last-Iterate Convergence of Optimistic Gradient Method for Monotone Variational Inequalities

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1. Preliminaries

Problem: variational inequality problem (VIP) – find $x^* \in \mathcal{X} \subseteq \mathbb{R}^d$ such that

$$\langle F(x^*), x - x^* \rangle \geq 0, \quad \forall x \in \mathcal{X}$$

Examples:

- Min-max problems

$$\min_{u \in U} \max_{v \in V} f(u, v)$$

- Minimization problems

$$\min_{x \in \mathcal{X}} f(x)$$

Assumptions: for all $x, y \in \mathcal{X}$ we assume

- **Lipschitzness** $\|F(x) - F(y)\| \leq L\|x - y\|$

- **Monotonicity** $\langle F(x) - F(y), x - y \rangle \geq 0$

Convergence metrics:

- Restricted gap function: for $R \sim \|x^0 - x^*\|$ it is defined as

$$\text{Gap}_F(x^N) = \max_{y \in \mathcal{X}: \|y - x^*\| \leq R} \langle F(y), x^N - y \rangle$$

- Squared norm of the residual/operator (constrained/unconstrained cases):

$$\|x^N - x^{N-1}\|^2 \quad \|F(x^N)\|^2$$

By default we report all results in terms of the squared norm of the residual

2. Extragradient and Past Extragradient

Extragradient method (EG) [Korpelevich, 1976]

$$\tilde{x}^k = \text{proj}[x^k - \gamma F(x^k)], \quad x^{k+1} = \text{proj}[x^k - \gamma F(\tilde{x}^k)]$$

- $\text{proj}[x] = \arg \min_{y \in \mathcal{X}} \|y - x\|$ – projection operator

Past Extragradient/Optimistic Gradient method (PEG) [Popov, 1980]

$$\tilde{x}^k = \text{proj}[x^k - \gamma F(\tilde{x}^{k-1})], \quad x^{k+1} = \text{proj}[x^k - \gamma F(\tilde{x}^k)]$$

In contrast to EG, PEG

- Requires only 1 operator call per iteration
- Is implementable as no-regret algorithm

Last-iterate convergence results for

EG

- $\mathcal{O}(1/N)$ bound in the unconstrained case [Gorbunov et al., 2022]
- $\mathcal{O}(1/N)$ bound in the constrained case [Cai et al., 2022]

PEG

- $\mathcal{O}(1/N)$ bound in the unconstrained case if additionally the Jacobian $\nabla F(x)$ is Δ -Lipschitz [Golowich et al., 2020]

3. Our Contributions

$\mathcal{O}(1/N)$ last-iterate convergence rate for PEG in terms of the squared norm of the residual for monotone and Lipschitz VIPs in constrained and unconstrained cases

- ✓ No additional assumptions are used
- ✓ Potential-based proof obtained via computer

4. Main Results

Unconstrained case

Key lemma: for any $k > 0$ the iterates of PEG satisfy

$$\Psi_{k+1} \leq \Psi_k - 3 \left(\frac{2}{9} - L^2 \gamma^2 \right) \|F(\tilde{x}^k) - F(\tilde{x}^{k-1})\|^2$$

$$\text{for } \Psi_k = \|F(x^k)\|^2 + 2 \|F(x^k) - F(\tilde{x}^{k-1})\|^2$$

- In contrast, **EG** has much simpler potential: $\Psi_k = \|F(x^k)\|^2$
- As we illustrate in the paper, $\|F(x^k)\|^2$ is not a potential for **PEG**, i.e., $\|F(x^k)\|^2$ can grow for **PEG**

Using this lemma and standard analysis of PEG, we derive the following result

Theorem: for any $k > 0$ the iterates of PEG with $\gamma \leq 1/3L$ satisfy

$$\Phi_{k+1} \leq \Phi_k, \quad \Phi_k = \|x^k - x^*\|^2 + \frac{k+32}{3} \gamma^2 \Psi_k$$

In particular, this implies

$$\|F(x^N)\|^2 = \mathcal{O}\left(\frac{R_0^2}{\gamma^2 N}\right) \quad \text{Gap}_F(x^N) = \mathcal{O}\left(\frac{R_0}{\gamma \sqrt{N}}\right)$$

Constrained case

Theorem: for any $k > 1$ the iterates of PEG with $\gamma \leq 1/4L$ satisfy

$$\Phi_{k+1} \leq \Phi_k$$

$$\Phi_k = \|x^k - x^*\|^2 + \frac{1}{16} \|\tilde{x}^{k-1} - \tilde{x}^{k-2}\|^2 + \frac{3k+32}{24} \Psi_k$$

$$\Psi_k = \|x^k - x^{k-1}\|^2 + \|x^k - x^{k-1} - 2\gamma(F(x^k) - F(\tilde{x}^{k-1}))\|^2$$

In particular, this implies

$$\|x^N - x^{N-1}\|^2 = \mathcal{O}\left(\frac{R_0^2}{N}\right) \quad \text{Gap}_F(x^N) = \mathcal{O}\left(\frac{R_0}{\gamma \sqrt{N}}\right)$$

- Analysis does not follow straightforwardly from the result in the unconstrained case

5. Path to the Proof

Below we illustrate the non-triviality of the analysis of PEG even for unconstrained VIPs.

To obtain the results below and the proofs most of the results in the paper we used Performance Estimation Problems technique [Taylor et al., 2017].

- The following problem gives the worst-case last-iterate guarantee for PEG

$$G_{\text{PEG}}(\gamma, L, N) = \max_{\substack{F, d, x^* \\ \tilde{x}^0, \dots, \tilde{x}^N \\ x^0, \dots, x^N}} \frac{\|F(x^N)\|^2}{\|x^0 - x^*\|^2}$$

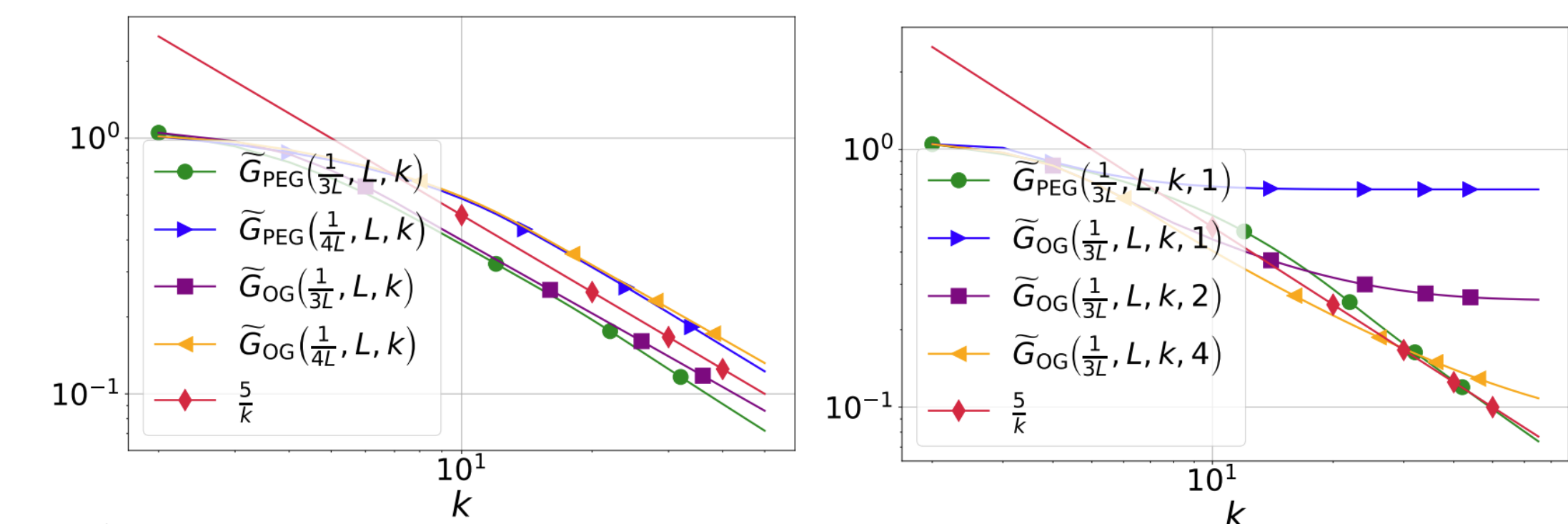
s.t. F is monotone and L -Lipschitz,
 $\tilde{x}^0 = x^0 \in \mathbb{R}^d, x^1 = x^0 - \gamma F(x^0)$
 $\tilde{x}^k = x^k - \gamma F(\tilde{x}^{k-1}), \text{ for } k = 1, \dots, N,$
 $x^{k+1} = x^k - \gamma F(\tilde{x}^k), \text{ for } k = 1, \dots, N-1$

- **Bad news:** problem is infinitely-dimensional \rightarrow hard to solve
- **Good news:** there exist an SDP relaxation that is easy to solve numerically
- SDP finds pairs $\{x^*, 0\}, \{x^k, g^k\}_{k=0}^N, \{\tilde{x}^k, \tilde{g}^k\}_{k=0}^N$ such that $g^k \approx F(x^k), \tilde{g}^k \approx F(\tilde{x}^k)$ and all Lipschitzness and monotonicity inequalities between these points hold
- This SDP has optimal value $\tilde{G}_{\text{PEG}}(\gamma, L, N) \geq G_{\text{PEG}}(\gamma, L, N)$. We numerically verified that $\tilde{G}_{\text{PEG}}(\gamma, L, N) = \mathcal{O}(1/N)$

In the unconstrained case, one can rewrite PEG in the Optimistic Gradient (OG) form

$$\tilde{x}^{k+1} = \tilde{x}^k - 2\gamma F(\tilde{x}^k) + \gamma F(\tilde{x}^{k-1})$$

- Does not use sequence $\{x^k\}_{k \geq 0}$, looks simpler
- Similarly to PEG, one can formulate SDP for OG and verify $\tilde{G}_{\text{OG}}(\gamma, L, N) = \mathcal{O}(1/N)$
- However, it is hard to find a simple proof for OG: consider SDPs $\tilde{G}_{\text{PEG}}(\gamma, L, N, t)$ and $\tilde{G}_{\text{OG}}(\gamma, L, N, t)$ obtained from $\tilde{G}_{\text{PEG}}(\gamma, L, N)$ and $\tilde{G}_{\text{OG}}(\gamma, L, N)$ via removing the constraints corresponding to the points from steps i, j such that $|i - j| > t$. While $\tilde{G}_{\text{PEG}}(\gamma, L, N, t) = \mathcal{O}(1/N)$, $\tilde{G}_{\text{OG}}(\gamma, L, N, t)$ does not even for $t = 4$.



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