Stochastic Spectral Descent Methods

Elnur Gasanov² Eduard Gorbunov² Dmitry Kovalev² Peter Richtárik^{1,2,3}

 1 King Abdullah University of Science and Technology (KAUST), Kingdom of Saudi Arabia

Dmitry KovalevPeter Richtarik²Moscow Institute of Physics and Technology (MIPT), Russia³ University of Edinburgh, United Kingdom

1. Introduction Consider the following optimization problem

 $\min_{x \in \mathbb{R}^n} f(x) := \frac{1}{2} x^\top \mathbf{A} x - b^\top x,$

where **A** is an $n \times n$ symmetric positive definite matrix. The problem has a unique solution: $x_* = \mathbf{A}^{-1}b$. We are interested in the case when n is huge (millions, billions). Note that f is (strongly) convex and quadratic.

2. Algorithm: Stochastic Descent

The state-of-the-art methods for convex optimization in huge dimensions are <u>randomized coordinate descent (RCD)</u> methods. We now describe a method which includes RCD as a special case: **stochastic descent (SD)**. SD is a

5. Numerical Experiments



special case of the **sketch-and-project** method developed in [1].

Algorithm 1 [1, 2] (Stochastic Descent). Parameter: some distribution \mathcal{D} over vectors in \mathbb{R}^n Initialization: Choose $x_0 \in \mathbb{R}^n$ for $t = 0, 1, 2 \dots$ do Draw a fresh sample s_t from \mathcal{D} $x_{t+1} \leftarrow x_t - \frac{s_t^{\top}(\mathbf{A}x_t - b)}{s_t^{\top}\mathbf{A}s_t}s_t$ end for

RCD is obtained as a special case by letting \mathcal{D} be a distribution over unit coordinate (i.e., basis) vectors in \mathbb{R}^n : $\{e_1, e_2, \cdots, e_n\}$:

 $s_t \sim \mathcal{D} \qquad \Leftrightarrow \qquad s_t = e_i \quad \text{with probability} \quad p_i > 0.$

Theorem 1 [1, 2]. Algorithm 1 converges linearly in expectation as $(1 - \rho_{\max})^t \|x_0 - x_*\|_{\mathbf{A}}^2 \leq \mathbb{E}_{s \sim \mathcal{D}}[\|x_t - x_*\|_{\mathbf{A}}^2] \leq (1 - \rho_{\min})^t \|x_0 - x_*\|_{\mathbf{A}}^2,$ where $\|x\|_{\mathbf{A}} = (x^\top \mathbf{A} x)^{1/2}, \mathbf{W} := \mathbb{E}_{s \sim \mathcal{D}} \left[\frac{\mathbf{A}^{1/2} s s^\top \mathbf{A}^{1/2}}{s^\top \mathbf{A} s}\right], \ \rho_{\max} = \lambda_{\max}(\mathbf{W}),$ $\rho_{\min} = \lambda_{\min}(\mathbf{W}).$ Moreover, $0 < \rho_{\min} \leq 1/n \text{ and } \rho_{\max} \leq 1.$

3. Research Question



RCD with probabilities $p_i = \mathbf{A}_{ii}/\text{Tr}(\mathbf{A})$ satisfies: $\rho_{\min} = \lambda_1/\text{Tr}(\mathbf{A})$, where λ_1 is the smallest eigenvalue of \mathbf{A} . When ρ_{\min} is small, RCD is slow. Can we modify RCD by utilizing some spectral information, if known, so that the rate gets improved?

4. New Algorithm

Let $\mathbf{A} = \sum_{i=1}^{n} \lambda_i u_i u_i^{\top}$ be the eigenvalue decomposition of \mathbf{A} , with $0 < \lambda_1 \leq \lambda_2 \leq \cdots \leq \lambda_n$ being the eigenvalues, and u_1, \ldots, u_n the eigenvectors.

Algorithm 2 (Stochastic Spectral Coordinate Descent). *Parameter:* Choose $k \in \{0, ..., n-1\}$; set $C_k = k\lambda_{k+1} + \sum_{i=k+1}^n \lambda_i$ Run Algorithm 1 with the following distribution \mathcal{D} :

$$s_t = \begin{cases} e_i & \text{with probability } p_i = \frac{\mathbf{A}_{ii}}{C_k}, \ i = 1, 2, \dots, n \\ u_i & \text{with probability } p_{n+i} = \frac{\lambda_{k+1} - \lambda_i}{C_k}, \ i = 1, 2, \dots, k \end{cases}$$

Note that for k = 0, Algorithm 2 reduces to RCD.

Theorem 2. For every $n \ge 2$, Algorithm 2 has the rate

$$ho_{\min} = rac{\lambda_{k+1}}{C_k}.$$

Moreover, the rate improves as k grows, and interpolates between the RCD rate $\lambda_1/\text{Tr}(\mathbf{A})$ for k = 0, and the optimal rate 1/n for k = n - 1: $\frac{\lambda_1}{\text{Tr}(\mathbf{A})} = \frac{\lambda_1}{C_0} \leq \cdots \leq \frac{\lambda_{k+1}}{C_k} \leq \cdots \leq \frac{\lambda_{n-1}}{C_{n-2}} \leq \frac{\lambda_n}{C_{n-1}} = \frac{1}{n}.$



uniform distribution on [10, 11] and half from uniform distribution on [50, 51] and half from uniform distribution on [100, 101]; n = 20 uniform distribution on [100, 101]; n = 20



6. Bibliography

The total work of Algorithm 2 depends on k:

$$Work(\mathcal{D}) := \underbrace{P(\mathcal{D})}_{\text{preprocessing cost}} + \underbrace{C(\mathcal{D})}_{\text{cost of 1 iteration}} \times \underbrace{I(\mathcal{D})}_{\text{number of iterations till ϵ-solution}$$

k	$P(\mathcal{D})$	$C(\mathcal{D})$	$I(\mathcal{D})$
0	O(n)	O(n)	$\frac{\text{Tr}(\mathbf{A})}{\lambda_1}\ln(1/\epsilon)$
0 < k < n - 1	computation of λ_i for $i = 1, 2, \dots, k+1$ computation of u_i for $i = 1, 2, \dots, k$	O(n)	$\frac{C_k}{\lambda_{k+1}}\ln(1/\epsilon)$
n-1	computation of λ_i for $i = 1, 2,, n$ computation of u_i for $i = 1, 2,, n - 1$	O(n)	$n \ln(1/\epsilon)$

 [1] R. M. Gower and P. Richtárik. Randomized iterative methods for linear systems. SIAM Journal on Matrix Analysis and Applications, 36(4):1660– 1690, 2015.

[2] P. Richtárik and M. Takáč. Stochastic reformulations of linear systems: Algorithms and convergence theory. *arXiv preprint arXiv:1706.01108*, 2017.



