

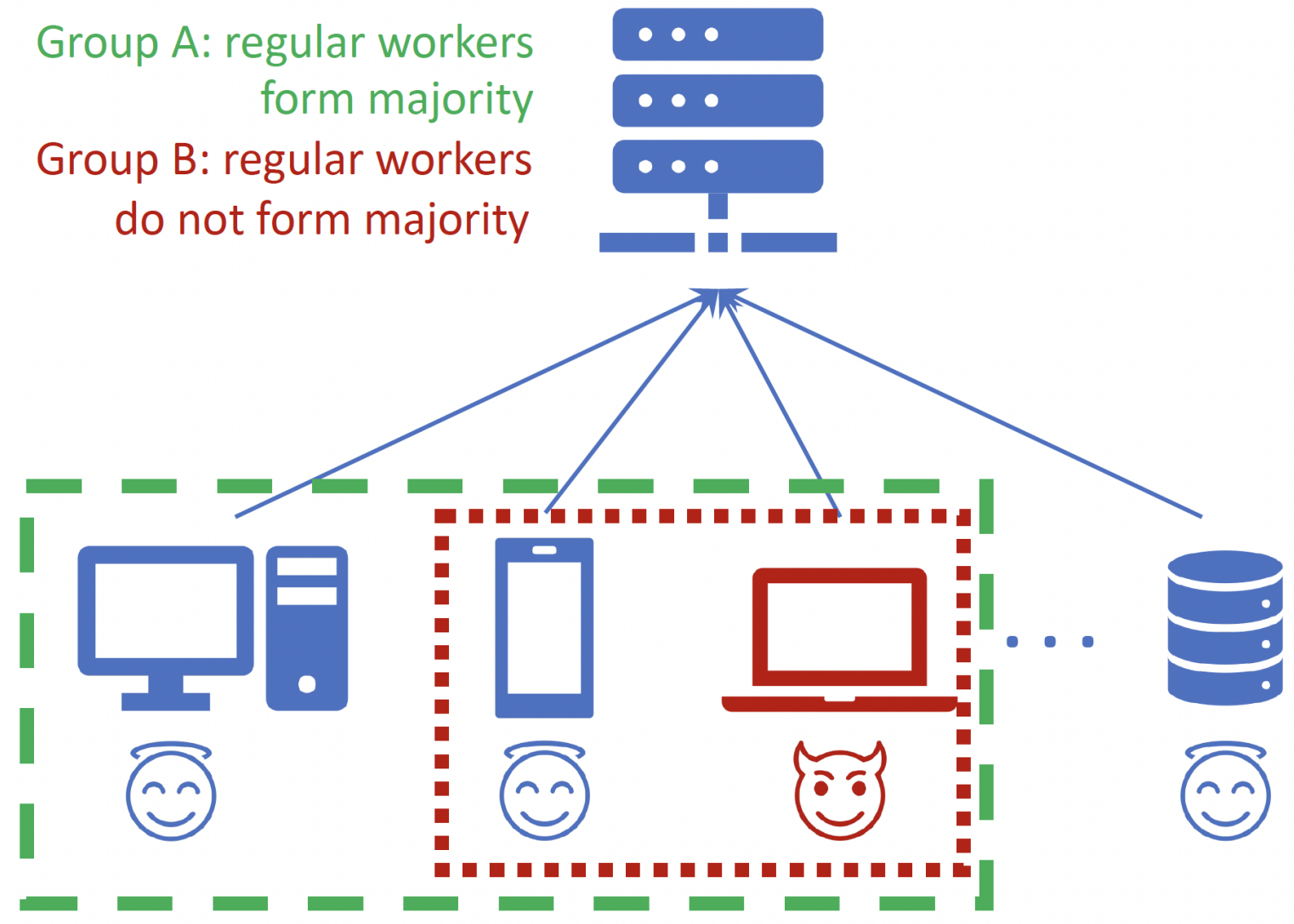
Byzantine Robustness and Partial Participation Can Be Achieved Simultaneously: Just Clip Gradient Differences

1. Byzantine-Robust Optimization

Distributed optimization problem:

$$\min_{x \in \mathbb{R}^d} \left\{ f(x) = \frac{1}{G} \sum_{i \in \mathcal{G}} f_i(x) \right\}, \quad f_i(x) = \frac{1}{m} \sum_{j=1}^m f_{i,j}(x) \quad \forall i \in \mathcal{G}$$

- \mathcal{G} is the set of **regular clients**
- \mathcal{B} is the set of **Byzantine workers** – the workers that can arbitrarily deviate from the prescribed protocol (maliciously or not) and are assumed to be omniscient
- $\mathcal{G} \sqcup \mathcal{B} = [n]$ is the set of clients participating in training



Main difficulties in Byzantine-robust optimization:

- When functions are arbitrarily heterogeneous, the problem is impossible to solve
- Fraction of Byzantines $\delta = B/n$ should be smaller than $1/2$
- Standard approaches based on averaging are vulnerable
- Robust aggregation alone does not ensure robustness [1]
- Non-triviality of partial participation:** *all existing approaches are vulnerable* to the situations when regular workers **do not form a majority** during some rounds

2. Robust Aggregation

Popular aggregation rules:

- Krum**(x_1, \dots, x_n) := $\operatorname{argmin}_{x_i \in \{x_1, \dots, x_n\}} \sum_{j \in S_i} \|x_j - x_i\|^2$ [7], where $S_i \subseteq \{x_1, \dots, x_n\}$ are $n - |\mathcal{B}| - 2$ closest vectors to x_i
 - Robust Fed. Averaging: **RFA**(x_1, \dots, x_n) := $\operatorname{argmin}_{x \in \mathbb{R}^d} \sum_{i=1}^n \|x - x_i\|$
 - Coordinate-wise Median: $[\mathbf{CM}(x_1, \dots, x_n)]_t := \operatorname{argmin}_{u \in \mathbb{R}} \sum_{i=1}^n |u - [x_i]_t|$
- These defenses are vulnerable to Byzantine attacks [8,9] and do not satisfy the following definition.**

Definition 1: (δ, c) -Robust Aggregator (modification of the definition from [1])
The quantity \hat{x} is (δ, c)-Robust Aggregator ((δ, c) -RAgg) if $\mathbb{E} \left[\ \hat{x} - \bar{x}\ ^2 \right] \leq c\delta\sigma^2, \quad \text{where} \quad (1)$ <ul style="list-style-type: none"> Input: $\{x_1, x_2, \dots, x_n\}$ There exists a subset $\mathcal{G} \subseteq [n]$ of size $\mathcal{G} = G \geq (1 - \delta)n$ for $\delta < 0.5$ such that $\frac{1}{G(G-1)} \sum_{i,l \in \mathcal{G}} \mathbb{E}[\ x_i - x_l\ ^2] \leq \sigma^2$ $\bar{x} = \frac{1}{ \mathcal{G} } \sum_{i \in \mathcal{G}} x_i$ \hat{x} is agnostic $((\delta, c)$-ARAgg), if it can be computed without knowledge of σ

One can robustify **Krum**, **RFA**, and **CM** using bucketing [1].

Algorithm Bucketing: Robust Aggregation using bucketing [1]

- Input:** $\{x_1, \dots, x_n\}$, $s \in \mathbb{N}$ – bucket size, **Aggr** – aggregator
- Sample random permutation** $\pi = (\pi(1), \dots, \pi(n))$ of $[n]$
- Compute** $y_i = \frac{1}{s} \sum_{k=s(i-1)+1}^{\min\{si, n\}} x_{\pi(k)}$ for $i = 1, \dots, \lceil n/s \rceil$
- Return:** $\hat{x} = \text{Aggr}(y_1, \dots, y_{\lceil n/s \rceil})$

Main Contributions

- New method: Byz-VR-MARINA-PP.** We develop Byzantine-tolerant Variance-Reduced MARINA with Partial Participation (Byz-VR-MARINA-PP) – **the first distributed method having Byzantine robustness and allowing partial participation of clients.**
- New convergence rates.** We derive convergence guarantees for the proposed method under mild assumptions.
- New application of gradient clipping.** The key tool that allows our method to withstand Byzantines attacks even when all sampled clients are Byzantine is clipping.

3. Ingredient 1: Variance Reduction

SGD: $x^{k+1} = x^k - \gamma g^k$, $g^k = \frac{1}{n} \sum_{i=1}^n \nabla f_{i,j_i^k}(x^k)$

- Variances of the estimators $\nabla f_{i,j_i^k}(x^k)$ do not go to zero
- Byzantines can easily hide in the noise and create a large bias (even if the aggregation is robust)

SAGA [2]: $x^{k+1} = x^k - \gamma g^k$, $g^k = \frac{1}{n} \sum_{i=1}^n g_i^k$,
 $g_i^k = \nabla f_{j_i^k}(x^k) - \nabla f_{i,j_i^k}(w_{i,j_i^k}^k) + \frac{1}{m} \sum_{j=1}^m \nabla f_{i,j}(w_{i,j}^k)$

- Variances of the estimators g_i^k go to zero
- Analysis relies on the unbiasedness: $\mathbb{E}[g_i^k | x^k] = \nabla f_i(x^k)$

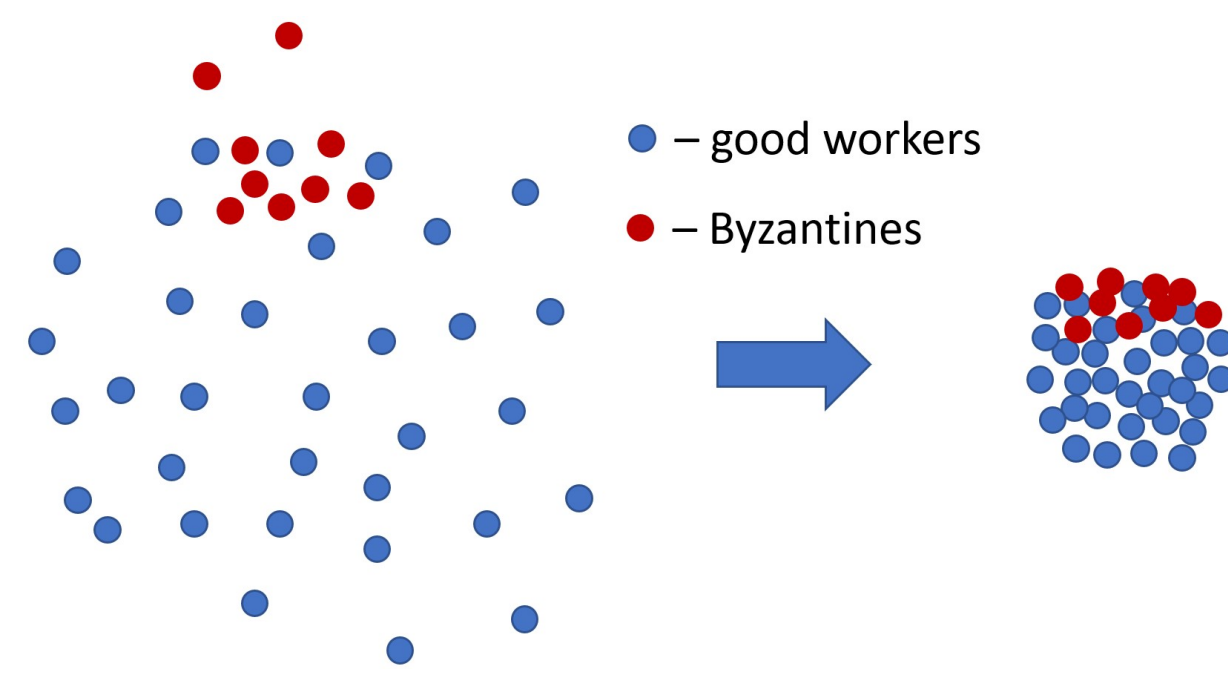
SARAH/Geom-SARAH/PAGE [3,4,5]:

$x^{k+1} = x^k - \gamma g^k$, $g^k = \frac{1}{n} \sum_{i=1}^n g_i^k$,

$g_i^k = \begin{cases} \nabla f_i(x^k), & \text{with prob. } p, \\ g_i^{k-1} + \nabla f_{i,j_i^k}(x^k) - \nabla f_{i,j_i^k}(x^{k-1}), & \text{with prob. } 1 - p \end{cases}$

- Variances of the estimators g_i^k go to zero
- Analysis does not rely on the unbiasedness: $\mathbb{E}[g_i^k | x^k] \neq \nabla f_i(x^k)$

How can variance reduction help? *It leaves less space for Byzantines to hide in the noise.*



4. Ingredient 2: Clipping

Clipping operator:

$$\text{clip}(x, \lambda) = \begin{cases} \min \left\{ 1, \frac{\lambda}{\|x\|} \right\} x, & \text{if } x \neq 0, \\ 0, & \text{otherwise.} \end{cases} \quad (2)$$

Properties of clipping:

- Boundedness: $\|\text{clip}(x, \lambda)\| \leq \lambda$
 - If the direction is spoiled, clipping ensures that the algorithm does not go far away even when Byzantines form majority
- Controlled bias: $\|\text{clip}(x, \lambda) - x\| \leq \left(1 - \min \left\{ 1, \frac{\lambda}{\|x\|} \right\} \right) \|x\|$
 - If the vector x is good enough, the right choice of the clipping level will not spoil the magnitude of the vector
 - Clipping preserves the direction

5. New Method: Byz-VR-MARINA-PP

Algorithm Byz-VR-MARINA-PP

- Input:** starting point x^0 , stepsize γ , minibatch size b , probability $p \in (0, 1]$, number of iterations K , (δ, c) -ARAgg, clients' sample size $1 \leq C \leq n$, clipping coefficients $\{\alpha_k\}_{k \geq 1}$, direction g^0
- for** $k = 0, 1, \dots, K - 1$ **do**
- Get a sample from Bernoulli distribution: $c_k \sim \text{Be}(p)$
- Sample the set of clients $S_k \subseteq [n]$, $|S_k| = C$ if $c_k = 0$; otherwise $S_k = [n]$
- Broadcast g^k , c_k to all workers
- for** $i \in \mathcal{G} \cap S_k$ in parallel **do**
- $x^{k+1} = x^k - \gamma g^k$ and $\lambda_{k+1} = \alpha_{k+1} \|x^{k+1} - x^k\|$
- Set $g_i^{k+1} = \begin{cases} \nabla f_i(x^{k+1}), & \text{if } c_k = 1, \\ g^k + \text{clip}_{\lambda_{k+1}} \left(\mathcal{Q} \left(\widehat{\Delta}_i(x^{k+1}, x^k) \right) \right), & \text{otherwise,} \end{cases}$ where $\widehat{\Delta}_i(x^{k+1}, x^k)$ is a minibatched estimator of $\nabla f_i(x^{k+1}) - \nabla f_i(x^k)$, $\mathcal{Q}(\cdot)$ for $i \in \mathcal{G} \cap S_k$ are computed independently
- end for**
- if** $c_k = 1$ **then**
- $g^{k+1} = \text{ARAgg}(\{g_i^{k+1}\}_{i \in [n]})$
- else**
- $g^{k+1} = g^k + \text{ARAgg} \left(\left\{ \text{clip}_{\lambda_{k+1}} \left(\mathcal{Q} \left(\widehat{\Delta}_i(x^{k+1}, x^k) \right) \right) \right\}_{i \in S_k} \right)$
- end if**
- end for**

- When $\alpha_k \equiv +\infty$ **Byz-VR-MARINA-PP** reduces to **Byz-VR-MARINA**
- \mathcal{Q} is a compression operator

- Clipping level is proportional to $\|x^{k+1} - x^k\|$, which is the key to controlling the bias

6. Technical Preliminaries

Definition 2: Unbiased Compression

Operator $\mathcal{Q} : \mathbb{R}^d \rightarrow \mathbb{R}^d$ is called unbiased compressor/compression operator if there exists $\omega \geq 0$ such that for any $x \in \mathbb{R}^d$

$$\mathbb{E}[\mathcal{Q}(x)] = x, \quad \mathbb{E}[\|\mathcal{Q}(x) - x\|^2] \leq \omega \|x\|^2. \quad (3)$$

Assumptions

- Bounded aggregator:** $\text{ARAgg}(x_1, \dots, x_n) \leq F \max_{i \in [n]} \|x_i\|$
- Smoothness and lower-boundedness:** $\forall x, y \in \mathbb{R}^d$ we have $\|\nabla f(x) - \nabla f(y)\| \leq L \|x - y\|$, $\|\nabla f_i(x) - \nabla f_i(y)\| \leq L_i \|x - y\|$ for $i \in \mathcal{G}$ and $f_* = \inf_{x \in \mathbb{R}^d} f(x) > -\infty$
- ζ^2 -heterogeneity: $\frac{1}{G} \sum_{i \in \mathcal{G}} \|\nabla f_i(x) - \nabla f(x)\|^2 \leq \zeta^2 \quad \forall x \in \mathbb{R}^d$
- Global Hessian variance assumption: $\frac{1}{G} \sum_{i \in \mathcal{G}} \|\nabla f_i(x) - \nabla f_i(y)\|^2 - \|\nabla f(x) - \nabla f(y)\|^2 \leq L_{\pm}^2 \|x - y\|^2$
- Local Hessian variance assumption:** $\frac{1}{G} \sum_{i \in \mathcal{G}} \mathbb{E}[\|\widehat{\Delta}_i(x, y) - \Delta_i(x, y)\|^2] \leq \frac{L_{\pm}^2}{b} \|x - y\|^2$, where $\Delta_i(x, y) = \nabla f_i(x) - \nabla f_i(y)$ and $\widehat{\Delta}_i(x, y)$ is an unbiased mini-batched estimator of $\Delta_i(x, y)$ with batch size b

7. Convergence Results

Theorem 1

Let the introduced assumptions hold and $\lambda_{k+1} = 2 \max_{i \in \mathcal{G}} L_i \|x^{k+1} - x^k\|$. Assume that $0 < \gamma \leq \frac{1}{L + \sqrt{A}}$, where

$$A = \frac{4}{p} \left(\frac{80 p_G \mathcal{P}_{\mathcal{G}_C^k} (1 - \delta) n}{C^2 (1 - \delta_{\max})^2} \omega + \frac{4}{p} (1 - p_G) + \frac{160}{p} p_G \mathcal{P}_{\mathcal{G}_C^k} c_{\delta_{\max}} \omega \right) L^2 + \frac{64}{p^2} (1 - p_G) F_{\Delta}^2 \max_{i \in \mathcal{G}} L_i^2 + \frac{4}{p} \left(\frac{8 p_G \mathcal{P}_{\mathcal{G}_C^k} (1 - \delta) n}{C^2 (1 - \delta_{\max})^2} (10\omega + 1) + \frac{16}{p} p_G \mathcal{P}_{\mathcal{G}_C^k} c_{\delta_{\max}} (10\omega + 1) \right) L_{\pm}^2 + \frac{4}{p} \left(\frac{80 p_G \mathcal{P}_{\mathcal{G}_C^k} (1 - \delta) n}{C^2 (1 - \delta_{\max})^2} (\omega + 1) + \frac{160}{p} p_G \mathcal{P}_{\mathcal{G}_C^k} c_{\delta_{\max}} (\omega + 1) \right) \frac{L_{\pm}^2}{b},$$

where $p_G := \mathbb{P}\{G_C^k \geq (1 - \delta_{\max})C\}$ and $\mathcal{P}_{\mathcal{G}_C^k} := \mathbb{P}\{i \in \mathcal{G}_C^k \mid G_C^k \geq (1 - \delta_{\max})C\}$. Then for all $K \geq 0$ the point \hat{x}^K chosen uniformly at random from the iterates x^0, x^1, \dots, x^K produced by Byz-VR-MARINA-PP satisfies

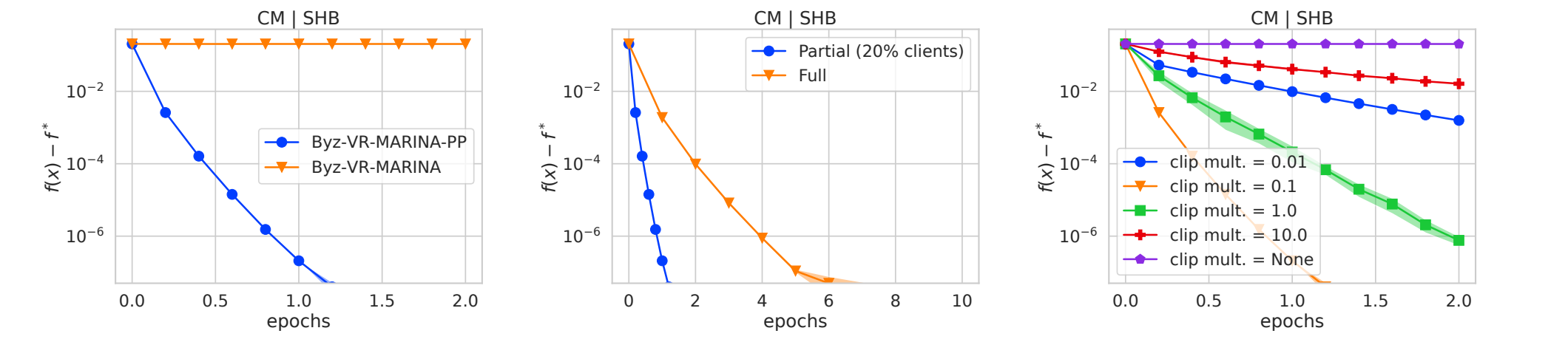
$$\mathbb{E}[\|\nabla f(\hat{x}^K)\|^2] \leq \frac{2\Phi_0}{\gamma(K+1)} + \frac{48c\delta\zeta^2}{p}, \quad (4)$$

where $\Phi_0 = f(x^0) - f_* + \frac{\gamma}{p} \|g^0 - \nabla f(x^0)\|^2$ and $\mathbb{E}[\cdot]$ denotes the full expectation.

- When $\zeta = 0$ (homogeneous data) the method converges asymptotically to the exact solution with rate $\mathcal{O}(1/k)$
- If $C = 1$, then $p_G = \frac{G}{C}$ and $\mathcal{P}_{\mathcal{G}_C^k} = \frac{1}{G}$; if $C = 2$, then $p_G = \frac{G(G-1)}{n(n-1)}$ and $\mathcal{P}_{\mathcal{G}_C^k} = \frac{2}{G}$; finally, if $C = n$, then $p_G = 1$ and $\mathcal{P}_{\mathcal{G}_C^k} = 1$
- Recommended value of $p = \min\{C/n, \eta/m, 1/(1+\omega)\}$

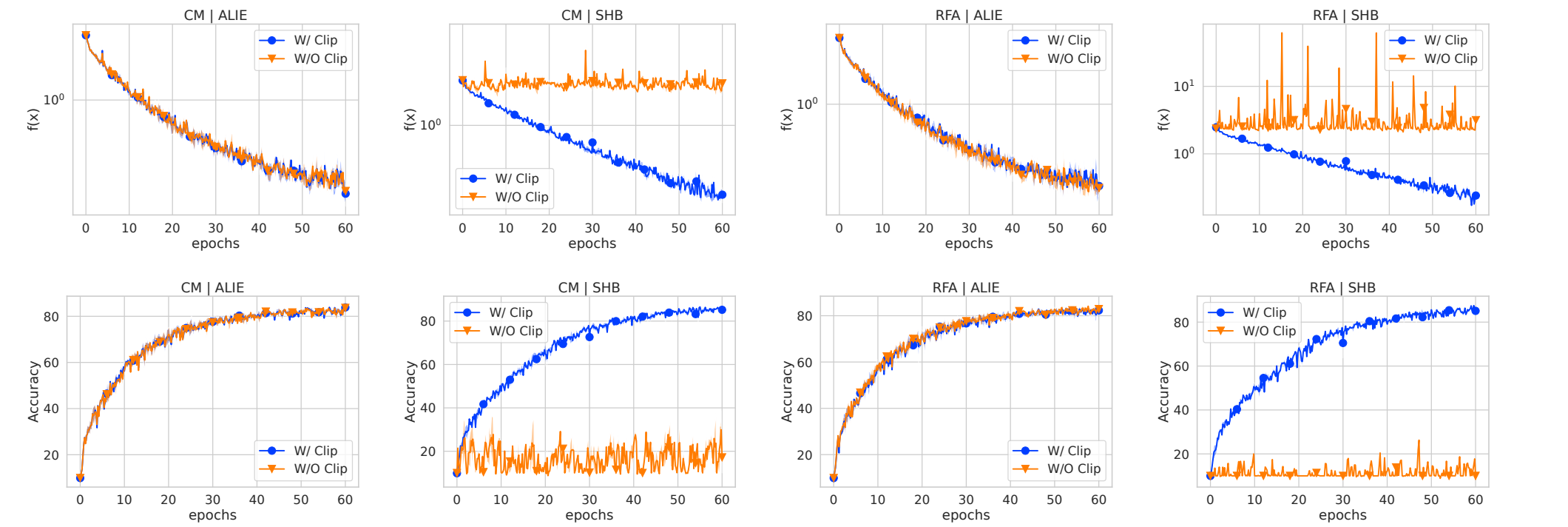
8. Experiments

- We consider a logistic regression model with ℓ_2 -regularization
- 15 good workers and 5 Byzantines; *access to the entire dataset*
- Aggregation: coordinate-wise median with bucketing
- Shift-back attack: if Byzantines form a majority during round k , then each Byzantine sends $x^0 - x^k$; otherwise, they follow protocol



Left: Linear convergence of Byz-VR-MARINA-PP with clipping versus non-convergence without clipping. Middle: Full versus partial participation. Right: Clipping multiplier α sensitivity.

- We consider a ResNet-18 model architecture with layer norm
- We consider the CIFAR 10 dataset with heterogeneous splits with 20 clients, 5 of which are Byzantines, and 4 clients are sampled in each step
- Attacks: we consider A Little is Enough (ALIE), Bit Flipping (BF), and Shift-Back (SHB) attacks
- Aggregation: we consider coordinate median (CM) and robust federated averaging (RFA) with bucketing.



Training loss (top) and test accuracy (bottom) of 2 aggregation rules (CM, RFA) under 4 attacks (BF, LF, ALIE, SHB) on the CIFAR10 dataset under heterogeneous data split with 20 clients, 5 of which are malicious, 4 clients sampled per round.

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